# A fixed point theorem for contractions in modular metric spaces ${ }^{\text {T }}$ 

Vyacheslav V. Chistyakova<br>${ }^{a}$ Department of Applied Mathematics and Computer Science, National Research University Higher School of Economics, Bol'shaya Pechërskaya Street 25/12, Nizhny Novgorod 603155, Russian Federation


#### Abstract

The notion of a (metric) modular on an arbitrary set and the corresponding modular space, more general than a metric space, were introduced and studied recently by the author [V.V. Chistyakov, Metric modulars and their application, Dokl. Math. 73 (1) (2006) 32-35, and Modular metric spaces, I: Basic concepts, Nonlinear Anal. 72 (1) (2010) 1-14]. In this paper we establish a fixed point theorem for contractive maps in modular spaces. It is related to contracting rather "generalized average velocities" than metric distances, and the successive approximations of fixed points converge to the fixed points in a weaker sense as compared to the metric convergence.


Key words: fixed point, metric modular, modular space, convex modular, modular convergence, modular completeness, modular contraction, mappings of bounded generalized $\varphi$-variation, $\Delta_{2}$-condition 2010 MSC: Primary: 47H10, 46A80, Secondary: 47H09, 54E35, 26A45

## 1. Introduction

The metric fixed point theory $([14,48])$ and its variations $([15])$ are farreaching developments of Banach's Contraction Principle, where metric conditions on the underlying space and maps under consideration play a fundamental role. This paper addresses fixed points of nonlinear maps in modular

[^0]spaces introduced recently by the author $([3]-10])$ as generalizations of Orlicz spaces and classical modular spaces ([19, 20], [22]-[27]), where modular structures (involving nonlinearities with more rapid growth than power-like functions), play the crucial role. Under different contractive assumptions and the supplementary $\Delta_{2}$-condition on modulars fixed point theorems in classical modular linear spaces were established in [1, 16, 17].

We begin with a certain motivation of the definition of a (metric) modular, introduced axiomatically in [7, 9]. A simple and natural way to do it is to turn to physical interpretations. Informally speaking, whereas a metric on a set represents nonnegative finite distances between any two points of the set, a modular on a set attributes a nonnegative (possibly, infinite valued) "field of (generalized) velocities": to each "time" $\lambda>0$ (the absolute value of) an average velocity $w_{\lambda}(x, y)$ is associated in such a way that in order to cover the "distance" between points $x, y \in X$ it takes time $\lambda$ to move from $x$ to $y$ with velocity $w_{\lambda}(x, y)$. Let us comment on this in more detail by exhibiting an appropriate example. If $d(x, y) \geq 0$ is the distance from $x$ to $y$ and a number $\lambda>0$ is interpreted as time, then the value

$$
\begin{equation*}
w_{\lambda}(x, y)=\frac{d(x, y)}{\lambda} \tag{1.1}
\end{equation*}
$$

is the average velocity, with which one should move from $x$ to $y$ during time $\lambda$, in order to cover the distance $d(x, y)$. The following properties of the quantity from (1.1) are quite natural.
(i) Two points $x$ and $y$ from $X$ coincide (and $d(x, y)=0$ ) if and only if any time $\lambda>0$ will do to move from $x$ to $y$ with velocity $w_{\lambda}(x, y)=0$ (i.e., no movement is needed at any time). Formally, given $x, y \in X$, we have:

$$
\begin{equation*}
x=y \text { iff } w_{\lambda}(x, y)=0 \text { for all } \lambda>0 \text { (nondegeneracy), } \tag{1.2}
\end{equation*}
$$

where 'iff' means as usual 'if and only if'.
(ii) Assuming the distance function to be symmetric, $d(x, y)=d(y, x)$, we find that for any time $\lambda>0$ the average velocity during the movement from $x$ to $y$ is the same as the average velocity in the opposite direction, i.e., for any $x, y \in X$ we have:

$$
\begin{equation*}
w_{\lambda}(x, y)=w_{\lambda}(y, x) \text { for all } \lambda>0 \text { (symmetry). } \tag{1.3}
\end{equation*}
$$

(iii) The third property of (1.1), which is, in a sense, a counterpart of the triangle inequality (for velocities!), is the most important. Suppose the
movement from $x$ to $y$ happens to be made in two different ways, but the duration of time is the same in each case: (a) passing through a third point $z \in X$, or (b) straightforward from $x$ to $y$. If $\lambda$ is the time needed to get from $x$ to $z$ and $\mu$ is the time needed to get from $z$ to $y$, then the corresponding average velocities are $w_{\lambda}(x, z)$ (during the movement from $x$ to $z$ ) and $w_{\mu}(z, y)$ (during the movement from $z$ to $y$ ). The total time needed for the movement in the case (a) is equal to $\lambda+\mu$. Thus, in order to move from $x$ to $y$ as in the case (b) one has to have the average velocity equal to $w_{\lambda+\mu}(x, y)$. Since (as a rule) the straightforward distance $d(x, y)$ does not exceed the sum of the distances $d(x, z)+d(z, y)$, it becomes clear from the physical intuition that the velocity $w_{\lambda+\mu}(x, y)$ does not exceed at least one of the velocities $w_{\lambda}(x, z)$ or $w_{\mu}(z, y)$. Formally, this is expressed as

$$
\begin{equation*}
w_{\lambda+\mu}(x, y) \leq \max \left\{w_{\lambda}(x, z), w_{\mu}(z, y)\right\} \leq w_{\lambda}(x, z)+w_{\mu}(z, y) \tag{1.4}
\end{equation*}
$$

for all points $x, y, z \in X$ and all times $\lambda, \mu>0$ ("triangle" inequality). In fact, these inequalities can be verified rigorously: if, on the contrary, we assume that $w_{\lambda}(x, z)<w_{\lambda+\mu}(x, y)$ and $w_{\mu}(z, y)<w_{\lambda+\mu}(x, y)$, then multiplying the first inequality by $\lambda$, the second inequality-by $\mu$, summing the results and taking into account (1.1), we find $d(x, z)=\lambda w_{\lambda}(x, z)<\lambda w_{\lambda+\mu}(x, y)$ and $d(z, y)=\mu w_{\mu}(z, y)<\mu w_{\lambda+\mu}(x, y)$, and it follows that $d(x, z)+d(z, y)<$ $(\lambda+\mu) w_{\lambda+\mu}(x, y)=d(x, y)$, which contradicts the triangle inequality for $d$.

Inequality (1.4) can be obtained in a little bit more general situation. Let $f:(0, \infty) \rightarrow(0, \infty)$ be a function from the set of positive reals into itself such that the function $\lambda \mapsto \lambda / f(\lambda)$ is nonincreasing on $(0, \infty)$. Setting $w_{\lambda}(x, y)=d(x, y) / f(\lambda)$ (note that $f(\lambda)=\lambda$ in (1.1)), we have

$$
\begin{align*}
w_{\lambda+\mu}(x, y) & =\frac{d(x, y)}{f(\lambda+\mu)} \leq \frac{d(x, z)+d(z, y)}{f(\lambda+\mu)} \leq \frac{\lambda}{\lambda+\mu} \cdot \frac{d(x, z)}{f(\lambda)}+\frac{\mu}{\lambda+\mu} \cdot \frac{d(z, y)}{f(\mu)} \leq \\
& \leq \frac{\lambda}{\lambda+\mu} w_{\lambda}(x, z)+\frac{\mu}{\lambda+\mu} w_{\mu}(z, y) \leq w_{\lambda}(x, z)+w_{\mu}(z, y) \tag{1.5}
\end{align*}
$$

A nonclassical example of "generalized velocities" satisfying (1.2)-(1.4) is given by: $w_{\lambda}(x, y)=\infty$ if $\lambda \leq d(x, y)$, and $w_{\lambda}(x, y)=0$ if $\lambda>d(x, y)$.

A (metric) modular on a set $X$ is any one-parameter family $w=\left\{w_{\lambda}\right\}_{\lambda>0}$ of functions $w_{\lambda}: X \times X \rightarrow[0, \infty]$ satisfying (1.2)-(1.4). In particular, the family given by (1.1) is the canonical (= natural) modular on a metric space $(X, d)$, which can be interpreted as a field of average velocities. For a different interpretation of modulars related to the joint generalized variation
of univariate maps and their relationships with classical modulars on linear spaces we refer to [9] (cf. also Section (4).

The difference between a metric (=distance function) and a modular on a set is now clearly seen: a modular depends on a positive parameter and may assume infinite values; the latter property means that it is impossible (or prohibited) to move from $x$ to $y$ in time $\lambda$, unless one moves with infinite velocity $w_{\lambda}(x, y)=\infty$. In addition (cf. (1.1)), the "velocity" $w_{\lambda}(x, y)$ is nonincreasing as a function of "time" $\lambda>0$. The knowledge of "average velocities" $w_{\lambda}(x, y)$ for all $\lambda>0$ and $x, y \in X$ provides more information than simply the knowledge of distances $d(x, y)$ between $x$ and $y$ : the distance $d(x, y)$ can be recovered as a "limit case" via the formula (again cf. (1.1)):

$$
d(x, y)=\inf \left\{\lambda>0: w_{\lambda}(x, y) \leq 1\right\}
$$

Now we describe briefly the main result of this paper. Given a modular $w$ on a set $X$, we introduce the modular space $X_{w}^{*}=X_{w}^{*}\left(x_{0}\right)$ around a point $x_{0} \in X$ as the set of those $x \in X$, for which $w_{\lambda}\left(x, x_{0}\right)$ is finite for some $\lambda=\lambda(x)>0$. A map $T: X_{w}^{*} \rightarrow X_{w}^{*}$ is said to be modular contractive if there exists a constant $0<k<1$ such that for all small enough $\lambda>0$ and all $x, y \in X_{w}^{*}$ we have $w_{k \lambda}(T x, T y) \leq w_{\lambda}(x, y)$. Our main result (Theorem 5.3) asserts that if $w$ is convex and strict, $X_{w}^{*}$ is modular complete (the emphasized notions will be introduced in the main text below) and $T: X_{w}^{*} \rightarrow X_{w}^{*}$ is modular contractive, then $T$ admits a (unique) fixed point: $T x_{*}=x_{*}$ for some $x_{*} \in X_{w}^{*}$. The successive approximations of $x_{*}$ constructed in the proof of this result converge to $x_{*}$ in the modular sense, which is weaker than the metric convergence. In particular, Banach's Contraction Principle follows if we take into account (1.1).

This paper is organized as follows. In Section 2 we study modulars and convex modulars and introduce two modular spaces. In Section 3 we introduce the notions of modular convergence, modular limit and modular completeness and show that they are "weaker" than the corresponding metric notions. These notions are illustrated in Section 4 by examples. Section 5 is devoted to a fixed point theorem for modular contractions in modular complete modular metric spaces. This theorem is then applied in Section 6 to the existence of solutions of a Carathéodory-type ordinary differential equation with the right-hand side from the Orlicz space $L^{\varphi}$. Finally, in Section 7 some concluding remarks are presented.

## 2. Modulars and modular spaces

In what follows $X$ is a nonempty set, $\lambda>0$ is understood in the sense that $\lambda \in(0, \infty)$ and, in view of the disparity of the arguments, functions $w:(0, \infty) \times X \times X \rightarrow[0, \infty]$ will be also written as $w_{\lambda}(x, y)=w(\lambda, x, y)$ for all $\lambda>0$ and $x, y \in X$, so that $w=\left\{w_{\lambda}\right\}_{\lambda>0}$ with $w_{\lambda}: X \times X \rightarrow[0, \infty]$.
Definition $2.1([7,[9])$. A function $w:(0, \infty) \times X \times X \rightarrow[0, \infty]$ is said to be a (metric) modular on $X$ if it satisfies the following three conditions:
(i) given $x, y \in X, x=y$ iff $w_{\lambda}(x, y)=0$ for all $\lambda>0$;
(ii) $w_{\lambda}(x, y)=w_{\lambda}(y, x)$ for all $\lambda>0$ and $x, y \in X$;
(iii) $w_{\lambda+\mu}(x, y) \leq w_{\lambda}(x, z)+w_{\mu}(y, z)$ for all $\lambda, \mu>0$ and $x, y, z \in X$.

If, instead of (i), the function $w$ satisfies only
(i') $w_{\lambda}(x, x)=0$ for all $\lambda>0$ and $x \in X$,
then $w$ is said to be a pseudomodular on $X$, and if $w$ satisfies ( $\mathrm{i}^{\prime}$ ) and
(is) given $x, y \in X$, if there exists a number $\lambda>0$, possibly depending on $x$ and $y$, such that $w_{\lambda}(x, y)=0$, then $x=y$, the function $w$ is called a strict modular on $X$.

A modular (pseudomodular, strict modular) $w$ on $X$ is said to be convex if, instead if (iii), for all $\lambda, \mu>0$ and $x, y, z \in X$ it satisfies the inequality
(iv) $w_{\lambda+\mu}(x, y) \leq \frac{\lambda}{\lambda+\mu} w_{\lambda}(x, z)+\frac{\mu}{\lambda+\mu} w_{\mu}(y, z)$.

A motivation of the notion of convexity for modulars, which may look unexpected at first glance, was given in [9, Theorem 3.11], cf. also inequality (1.5); a further generalization of this notion was presented in [8, Section 5].

Given a metric space $(X, d)$ with metric $d$, two canonical strict modulars are associated with it: $w_{\lambda}(x, y)=d(x, y)$ (denoted simply by $d$ ), which is independent of the first argument $\lambda$ and is a (nonconvex) modular on $X$ in the sense of (i)-(iii), and the convex modular (1.1), which satisfies (i), (ii) and (iv). Both modulars $d$ and (1.1) assume only finite values on $X$.

Clearly, if $w$ is a strict modular, then $w$ is a modular, which in turn implies $w$ is a pseudomodular on $X$, and similar implications hold for convex $w$.

The essential property of a pseudomodular $w$ on $X$ (cf. [9, Section 2.3]) is that, for any given $x, y \in X$, the function $0<\lambda \mapsto w_{\lambda}(x, y) \in[0, \infty]$ is nonincreasing on $(0, \infty)$, and so, the limit from the right $w_{\lambda+0}(x, y)$ and the limit from the left $w_{\lambda-0}(x, y)$ exist in $[0, \infty]$ and satisfy the inequalities:

$$
\begin{equation*}
w_{\lambda+0}(x, y) \leq w_{\lambda}(x, y) \leq w_{\lambda-0}(x, y) \tag{2.1}
\end{equation*}
$$

A convex pseudomodular $w$ on $X$ has the following additional property: given $x, y \in X$, we have (cf. [9, Section 3.5]):

$$
\begin{equation*}
\text { if } 0<\mu \leq \lambda \text {, then } w_{\lambda}(x, y) \leq \frac{\mu}{\lambda} w_{\mu}(x, y) \leq w_{\mu}(x, y) \tag{2.2}
\end{equation*}
$$

i.e., functions $\lambda \mapsto w_{\lambda}(x, y)$ and $\lambda \mapsto \lambda w_{\lambda}(x, y)$ are nonincresing on $(0, \infty)$.

Throughout the paper we fix an element $x_{0} \in X$ arbitrarily.
Definition $2.2([\mathbf{7}, \mathbf{9}])$. Given a pseudomodular $w$ on $X$, the two sets

$$
X_{w} \equiv X_{w}\left(x_{0}\right)=\left\{x \in X: w_{\lambda}\left(x, x_{0}\right) \rightarrow 0 \text { as } \lambda \rightarrow \infty\right\}
$$

and

$$
X_{w}^{*} \equiv X_{w}^{*}\left(x_{0}\right)=\left\{x \in X: \exists \lambda=\lambda(x)>0 \text { such that } w_{\lambda}\left(x, x_{0}\right)<\infty\right\}
$$

are said to be modular spaces (around $x_{0}$ ).
It is clear that $X_{w} \subset X_{w}^{*}$, and it is known (cf. [9, Sections 3.1, 3.2]) that this inclusion is proper in general. It follows from [9, Theorem 2.6] that if $w$ is a modular on $X$, then the modular space $X_{w}$ can be equipped with a (nontrivial) metric $d_{w}$, generated by $w$ and given by

$$
\begin{equation*}
d_{w}(x, y)=\inf \left\{\lambda>0: w_{\lambda}(x, y) \leq \lambda\right\}, \quad x, y \in X_{w} \tag{2.3}
\end{equation*}
$$

It will be shown later that $d_{w}$ is a well defined metric on a larger set $X_{w}^{*}$.
If $w$ is a convex modular on $X$, then according to [9, Section 3.5 and Theorem 3.6] the two modular spaces coincide, $X_{w}=X_{w}^{*}$, and this common set can be endowed with a metric $d_{w}^{*}$ given by

$$
\begin{equation*}
d_{w}^{*}(x, y)=\inf \left\{\lambda>0: w_{\lambda}(x, y) \leq 1\right\}, \quad x, y \in X_{w}^{*} \tag{2.4}
\end{equation*}
$$

moreover, $d_{w}^{*}$ is specifically equivalent to $d_{w}$ (see [9, Theorem 3.9]). By the convexity of $w$, the function $\widehat{w}_{\lambda}(x, y)=\lambda w_{\lambda}(x, y)$ is a modular on $X$ in the sense of (i)-(iii) and (cf. [9, formula (3.3)])

$$
\begin{equation*}
X_{\widehat{w}}^{*}=X_{w}^{*}=X_{w} \supset X_{\widehat{w}} \tag{2.5}
\end{equation*}
$$

where the last inclusion may be proper; moreover, $d_{\widehat{w}}=d_{w}^{*}$ on $X_{\widehat{w}}$.

Even if $w$ is a nonconvex modular on $X$, the quantity (2.4) is also defined for all $x, y \in X_{w}^{*}$, but it has only few properties (cf. [9, Theorem 3.6]): $d_{w}^{*}(x, x)=0$ and $d_{w}^{*}(x, y)=d_{w}^{*}(y, x)$. In this case we have (cf. [9, Theorem 3.9 and Example 3.10]): if $d_{w}(x, y)<1$, then $d_{w}^{*}(x, y) \leq d_{w}(x, y)$, and if $d_{w}^{*}(x, y) \geq 1$, then $d_{w}(x, y) \leq d_{w}^{*}(x, y)$.

Let us illustrate the above in the case of a metric space $(X, d)$ with the two canonical modulars $d$ and $w$ from (1.1) on it. We have: $X_{d}=\left\{x_{0}\right\} \subset$ $X_{d}^{*}=X_{w}=X_{w}^{*}=X$, and given $x, y \in X, d_{d}(x, y)=d(x, y), d_{d}^{*}(x, y)=0$, $d_{w}(x, y)=\sqrt{d(x, y)}, d_{w}^{*}(x, y)=d(x, y)$ and $\widehat{d}(x, y)=\lambda w_{\lambda}(x, y)=d(x, y)$. Thus, the convex modular $w$ from (1.1) plays a more adequate role in restoring the metric space $(X, d)$ from $w\left(c f . d_{w}^{*}=d\right.$ on $X_{w}=X_{w}^{*}=X$, whereas $X_{d} \subset X_{d}^{*}=X, d_{d}=d$ and $d_{d}^{*}=0$ ), and so, in what follows any metric space ( $X, d$ ) will be considered equipped only with the modular (1.1). This convention is also justified as follows.

Now we exhibit the relationship between convex and nonconvex modulars and show that $d_{w}$ is a well defined metric on $X_{w}^{*}$ (and not only on $X_{w}$ ). If $w$ is a (not necessarily convex) modular on $X$, then the function (cf. (1.1) where $d(x, y)$ plays the role of a modular)

$$
v_{\lambda}(x, y)=\frac{w_{\lambda}(x, y)}{\lambda}, \quad \lambda>0, \quad x, y \in X
$$

is always a convex modular on $X$. In fact, conditions (i) and (ii) are clear for $v$ and, as for (iv), we have, by virtue of (iii) for $w$ :

$$
\begin{aligned}
v_{\lambda+\mu}(x, y) & =\frac{w_{\lambda+\mu}(x, y)}{\lambda+\mu} \leq \frac{w_{\lambda}(x, z)+w_{\mu}(y, z)}{\lambda+\mu}= \\
& =\frac{\lambda}{\lambda+\mu} \cdot \frac{w_{\lambda}(x, z)}{\lambda}+\frac{\mu}{\lambda+\mu} \cdot \frac{w_{\mu}(y, z)}{\mu}=\frac{\lambda}{\lambda+\mu} v_{\lambda}(x, z)+\frac{\mu}{\lambda+\mu} v_{\mu}(y, z) .
\end{aligned}
$$

Moreover, because $w=\widehat{v}$, we find from (2.5) that $X_{w} \subset X_{w}^{*}=X_{v}=X_{v}^{*}$. Since $d_{v}^{*}(x, y)=\inf \left\{\lambda>0: w_{\lambda}(x, y) / \lambda \leq 1\right\}=d_{w}(x, y)$ for all $x, y \in X_{w}^{*}$, i.e., $d_{v}^{*}=d_{w}$ on $X_{w}^{*}$, and $d_{v}^{*}$ is a metric on $X_{v}^{*}=X_{w}^{*}$, then we conclude that $d_{w}$ is a well defined metric on $X_{w}^{*}$ (the same conclusion follows immediately from [8, Theorem 1]) with $X^{\prime}=X_{w}^{*}$ ). This property distinguishes our theory of modulars from the classical theory: if $\rho$ is a classical modular on a linear space $X$ in the sense of Musielak and Orlicz ([22]) and $w_{\lambda}(x, y)=\rho((x-y) / \lambda), \lambda>0$, $x, y \in X$, then the expression $v_{\lambda}(x, y)=(1 / \lambda) w_{\lambda}(x, y)=(1 / \lambda) \rho((x-y) / \lambda)$
is not allowed as a classical modular on $X$. Since $v$ is convex and $d_{v}^{*}=d_{w}$ on $X_{w}^{*}$, given $x, y \in X_{w}^{*}$, by virtue of [9, Theorem 3.9], we have:

$$
\begin{aligned}
& d_{w}(x, y)<1 \text { iff } d_{v}(x, y)<1, \text { and } d_{w}(x, y) \leq d_{v}(x, y) \leq \sqrt{d_{w}(x, y)} \\
& d_{w}(x, y) \geq 1 \text { iff } d_{v}(x, y) \geq 1, \text { and } \sqrt{d_{w}(x, y)} \leq d_{v}(x, y) \leq d_{w}(x, y)
\end{aligned}
$$

More metrics can be defined on $X_{w}^{*}$ for a given modular $w$ on $X$ in the following general way (cf. [8, Theorem 1]): if $\mathbb{R}^{+}=[0, \infty)$ and $\kappa: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$ is superadditive (i.e., $\kappa(\lambda)+\kappa(\mu) \leq \kappa(\lambda+\mu)$ for all $\lambda, \mu \geq 0$ ) and such that $\kappa(u)>0$ for $u>0$ and $\kappa(+0)=\lim _{u \rightarrow+0} \kappa(u)=0$, then the function $d_{\kappa, w}(x, y)=\inf \left\{\lambda>0: w_{\lambda}(x, y) \leq \kappa(\lambda)\right\}$ is a well defined metric on $X_{w}^{*}$.

Given a pseudomodular (modular, strict modular, convex or not) $w$ on $X, \lambda>0$ and $x, y \in X$, we define the left and right regularizations of $w$ by

$$
w_{\lambda}^{-}(x, y)=w_{\lambda-0}(x, y) \quad \text { and } \quad w_{\lambda}^{+}(x, y)=w_{\lambda+0}(x, y) .
$$

Since, by (2.1), $w_{\lambda}^{+}(x, y) \leq w_{\lambda}(x, y) \leq w_{\lambda}^{-}(x, y)$, and

$$
\begin{equation*}
w_{\lambda_{2}}^{-}(x, y) \leq w_{\lambda}(x, y) \leq w_{\lambda_{1}}^{+}(x, y) \quad \text { for all } \quad 0<\lambda_{1}<\lambda<\lambda_{2}, \tag{2.6}
\end{equation*}
$$

it is a routine matter to verify that $w^{-}$and $w^{+}$are pseudomodulars (modulars, strict modulars, convex or not, respectively) on $X, X_{w^{-}}=X_{w}=X_{w^{+}}$, $X_{w^{-}}^{*}=X_{w}^{*}=X_{w^{+}}^{*}, d_{w^{-}}=d_{w}=d_{w^{+}}$on $X_{w}$ and $d_{w^{-}}^{*}=d_{w}^{*}=d_{w^{+}}^{*}$ on $X_{w}^{*}$. For instance, let us check the last two equalities for metrics. Given $x, y \in X_{w}^{*}$, by virtue of (2.1), we find $d_{w^{-}}^{*}(x, y) \geq d_{w}^{*}(x, y) \geq d_{w^{+}}^{*}(x, y)$. In order to see that $d_{w^{-}}^{*}(x, y) \leq d_{w}^{*}(x, y)$, we let $\lambda>d_{w}^{*}(x, y)$ be arbitrary, choose $\mu$ such that $d_{w}^{*}(x, y)<\mu<\lambda$, which, by (2.6), gives $w_{\lambda}^{-}(x, y) \leq w_{\mu}(x, y) \leq 1$, and so, $d_{w^{-}}^{*}(x, y) \leq \lambda$, and then let $\lambda \rightarrow d_{w}^{*}(x, y)$. In order to prove that $d_{w}^{*}(x, y) \leq d_{w^{+}}^{*}(x, y)$, we let $\lambda>d_{w^{+}}^{*}(x, y)$ be arbitrary, choose $\mu$ such that $d_{w^{+}}^{*}(x, y)<\mu<\lambda$, which, by (2.6), implies $w_{\lambda}(x, y) \leq w_{\mu}^{+}(x, y) \leq 1$, and so, $d_{w}^{*}(x, y) \leq \lambda$, and then let $\lambda \rightarrow d_{w^{+}}^{*}(x, y)$.

In this way we have seen that the regularizations provide no new modular spaces as compared to $X_{w}$ and $X_{w}^{*}$ and no new metrics as compared to $d_{w}$ and $d_{w}^{*}$. The right regularization will be needed in Section 5 for the characterization of metric Lipschitz maps in terms of underlying modulars.

## 3. Sequences in modular spaces and modular convergence

The notions of modular convergence, modular limit, modular completeness, etc., which we study in this section, are known in the classical theory of
modulars on linear spaces (e.g., [20, 22, 25, 27]). Since the theory of (metric) modulars from [7]-[10] is significantly more general than the classical theory, the notions mentioned above do not carry over to metric modulars in a straightforward way and ought to be reintroduced and justified.

Definition 3.1. Given a pseudomodular $w$ on $X$, a sequence of elements $\left\{x_{n}\right\} \equiv\left\{x_{n}\right\}_{n=1}^{\infty}$ from $X_{w}$ or $X_{w}^{*}$ is said to be modular convergent (more precisely, $w$-convergent) to an element $x \in X$ if there exists a number $\lambda>0$, possibly depending on $\left\{x_{n}\right\}$ and $x$, such that $\lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0$. This will be written briefly as $x_{n} \xrightarrow{w} x$ (as $n \rightarrow \infty$ ), and any such element $x$ will be called a modular limit of the sequence $\left\{x_{n}\right\}$.

Note that if $\lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0$, then by virtue of the monotonicity of the function $\lambda^{\prime} \mapsto w_{\lambda^{\prime}}\left(x_{n}, x\right)$, we have: $\lim _{n \rightarrow \infty} w_{\mu}\left(x_{n}, x\right)=0$ for all $\mu \geq \lambda$.

It is clear for a metric space $(X, d)$ and the modular (1.1) on it that the metric convergence and the modular convergence in $X$ coincide.

We are going to show that the modular convergence is much weaker than the metric convergence (in the sense to be made more precise below). First, we study to what extent the above definition is correct, and what is the relationship between the modular and metric convergences in $X_{w}$ and $X_{w}^{*}$.

Theorem 3.1. Let $w$ be a pseudomodular on $X$. We have:
(a) the modular spaces $X_{w}$ and $X_{w}^{*}$ are closed with respect to the modular convergence, i.e., if $\left\{x_{n}\right\} \subset X_{w}\left(\right.$ or $\left.X_{w}^{*}\right), x \in X$ and $x_{n} \xrightarrow{w} x$, then $x \in X_{w}$ (or $x \in X_{w}^{*}$, respectively);
(b) if $w$ is a strict modular on $X$, then the modular limit is determined uniquely (if it exists).

Proof. (a) Since $x_{n} \xrightarrow{w} x$, there exists a $\lambda_{0}=\lambda_{0}\left(\left\{x_{n}\right\}, x\right)>0$ such that $w_{\lambda_{0}}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$.

1. First we treat the case when $\left\{x_{n}\right\} \subset X_{w}$. Let $\varepsilon>0$ be arbitrarily fixed. Then there is an $n_{0}=n_{0}(\varepsilon) \in \mathbb{N}$ such that $w_{\lambda_{0}}\left(x_{n_{0}}, x\right) \leq \varepsilon / 2$. Since $x_{n_{0}} \in X_{w}=X_{w}\left(x_{0}\right)$, we have $w_{\lambda}\left(x_{n_{0}}, x_{0}\right) \rightarrow 0$ as $\lambda \rightarrow \infty$, and so, there exists a $\lambda_{1}=\lambda_{1}(\varepsilon)>0$ such that $w_{\lambda_{1}}\left(x_{n_{0}}, x_{0}\right) \leq \varepsilon / 2$. Then conditions (iii) and (ii) from Definition 2.1 imply

$$
w_{\lambda_{0}+\lambda_{1}}\left(x, x_{0}\right) \leq w_{\lambda_{0}}\left(x, x_{n_{0}}\right)+w_{\lambda_{1}}\left(x_{0}, x_{n_{0}}\right) \leq \varepsilon .
$$

The function $\lambda \mapsto w_{\lambda}\left(x, x_{0}\right)$ is nonincreasing on $(0, \infty)$, and so,

$$
w_{\lambda}\left(x, x_{0}\right) \leq w_{\lambda_{0}+\lambda_{1}}\left(x, x_{0}\right) \leq \varepsilon \quad \text { for all } \quad \lambda \geq \lambda_{0}+\lambda_{1}
$$

implying $w_{\lambda}\left(x, x_{0}\right) \rightarrow 0$ as $\lambda \rightarrow \infty$, i.e., $x \in X_{w}$.
2. Now suppose that $\left\{x_{n}\right\} \subset X_{w}^{*}$. Then there exists an $n_{0} \in \mathbb{N}$ such that $w_{\lambda_{0}}\left(x_{n_{0}}, x\right) \leq 1$. Since $x_{n_{0}} \in X_{w}^{*}=X_{w}^{*}\left(x_{0}\right)$, there is a $\lambda_{1}>0$ such that $w_{\lambda_{1}}\left(x_{n_{0}}, x_{0}\right)<\infty$. Now it follows from conditions (iii) and (ii) that

$$
w_{\lambda_{0}+\lambda_{1}}\left(x, x_{0}\right) \leq w_{\lambda_{0}}\left(x, x_{n_{0}}\right)+w_{\lambda_{1}}\left(x_{0}, x_{n_{0}}\right)<\infty,
$$

and so, $x \in X_{w}^{*}$.
(b) Let $\left\{x_{n}\right\} \subset X_{w}$ or $X_{w}^{*}$ and $x, y \in X$ be such that $x_{n} \xrightarrow{w} x$ and $x_{n} \xrightarrow{w} y$. By the definition of the modular convergence, there exist $\lambda=\lambda\left(\left\{x_{n}\right\}, x\right)>0$ and $\mu=\mu\left(\left\{x_{n}\right\}, y\right)>0$ such that $w_{\lambda}\left(x_{n}, x\right) \rightarrow 0$ and $w_{\mu}\left(x_{n}, y\right) \rightarrow 0$ as $n \rightarrow \infty$. By conditions (iii) and (ii),

$$
w_{\lambda+\mu}(x, y) \leq w_{\lambda}\left(x, x_{n}\right)+w_{\mu}\left(y, x_{n}\right) \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty .
$$

It follows that $w_{\lambda+\mu}(x, y)=0$, and so, by condition ( $\mathrm{i}_{\mathrm{s}}$ ) from Definition 2.1, we get $x=y$.

It was shown in [9, Theorem 2.13] that if $w$ is a modular on $X$, then for $\left\{x_{n}\right\} \subset X_{w}$ and $x \in X_{w}$ we have:

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d_{w}\left(x_{n}, x\right)=0 \quad \text { iff } \quad \lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0 \text { for all } \lambda>0 \tag{3.1}
\end{equation*}
$$

and so, the metric convergence (with respect to the metric $d_{w}$ ) implies the modular convergence (cf. Definition 3.1), but not vice versa in general. As the proof of [9, Theorem 2.13] suggests, (3.1) is also true for $\left\{x_{n}\right\} \subset X_{w}^{*}$ and $x \in X_{w}^{*}$. An assertion similar to (3.1) holds for Cauchy sequences from the modular spaces $X_{w}$ and $X_{w}^{*}$.

Now we establish a result similar to (3.1) for convex modulars.
Theorem 3.2. Let $w$ be a convex modular on $X$. Given a sequence $\left\{x_{n}\right\}$ from $X_{w}^{*}\left(=X_{w}\right)$ and an element $x \in X_{w}^{*}$, we have:

$$
\lim _{n \rightarrow \infty} d_{w}^{*}\left(x_{n}, x\right)=0 \quad \text { iff } \quad \lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0 \text { for all } \lambda>0
$$

A similar assertion holds for Cauchy sequences with respect to $d_{w}^{*}$.

Proof. Step 1. Sufficiency. Given $\varepsilon>0$, by the assumption, there exists a number $n_{0}(\varepsilon) \in \mathbb{N}$ such that $w_{\varepsilon}\left(x_{n}, x\right) \leq 1$ for all $n \geq n_{0}(\varepsilon)$, and so, the definition (2.4) of $d_{w}^{*}$ implies $d_{w}^{*}\left(x_{n}, x\right) \leq \varepsilon$ for all $n \geq n_{0}(\varepsilon)$.

Necessity. First, suppose that $0<\lambda \leq 1$. Given $\varepsilon>0$, we have: either (a) $\varepsilon<\lambda$, or (b) $\varepsilon \geq \lambda$. In case (a), by the assumption, there is an $n_{0}(\varepsilon) \in \mathbb{N}$ such that $d_{w}^{*}\left(x_{n}, x\right)<\varepsilon^{2}$ for all $n \geq n_{0}(\varepsilon)$, and so, by the definition of $d_{w}^{*}$, $w_{\varepsilon^{2}}\left(x_{n}, x\right) \leq 1$ for all $n \geq n_{0}(\varepsilon)$. Since $\varepsilon^{2}<\lambda^{2} \leq \lambda$ and $\varepsilon<\lambda$, inequality (2.2) yields:

$$
w_{\lambda}\left(x_{n}, x\right) \leq \frac{\varepsilon^{2}}{\lambda} w_{\varepsilon^{2}}\left(x_{n}, x\right) \leq \frac{\varepsilon}{\lambda} \varepsilon<\varepsilon \quad \text { for all } \quad n \geq n_{0}(\varepsilon) .
$$

In case (b) we set $n_{1}(\varepsilon)=n_{0}(\lambda / 2)$, where $n_{0}(\cdot)$ is as above. Then, as we have just established, $w_{\lambda}\left(x_{n}, x\right)<\lambda / 2 \leq \varepsilon / 2<\varepsilon$ for all $n \geq n_{1}(\varepsilon)$.

Now, assume that $\lambda>1$. Again, given $\varepsilon>0$, we have: either (a) $\varepsilon<\lambda$, or (b) $\varepsilon \geq \lambda$. In case (a) there is an $N_{0}(\varepsilon) \in \mathbb{N}$ such that $d_{w}^{*}\left(x_{n}, x\right)<\varepsilon$ for all $n \geq N_{0}(\varepsilon)$, and so, $w_{\varepsilon}\left(x_{n}, x\right) \leq 1$ for all $n \geq N_{0}(\varepsilon)$. Since $\varepsilon<\lambda$ and $\lambda>1$, by virtue of (2.2), we find

$$
w_{\lambda}\left(x_{n}, x\right) \leq \frac{\varepsilon}{\lambda} w_{\varepsilon}\left(x_{n}, x\right) \leq \frac{\varepsilon}{\lambda}<\varepsilon \quad \text { for all } \quad n \geq N_{0}(\varepsilon)
$$

In case (b) we put $N_{1}(\varepsilon)=N_{0}(\lambda / 2)$, where $N_{0}(\cdot)$ is as above. Then it follows that $w_{\lambda}\left(x_{n}, x\right)<\lambda / 2 \leq \varepsilon / 2<\varepsilon$ for all $n \geq N_{1}(\varepsilon)$.

Thus, we have shown that $w_{\lambda}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$ for all $\lambda>0$.
Step 2. The assertion for Cauchy sequences is of the form:

$$
\lim _{n, m \rightarrow \infty} d_{w}^{*}\left(x_{n}, x_{m}\right)=0 \quad \text { iff } \quad \lim _{n, m \rightarrow \infty} w_{\lambda}\left(x_{n}, x_{m}\right)=0 \text { for all } \lambda>0
$$

its proof is similar to the one given in Step 1 with suitable modifications.
Theorem 3.2 shows, in particular, that in a metric space $(X, d)$ with modular (1.1) on it the metric and modular convergences are equivalent.

Definition 3.2. A pseudomodular $w$ on $X$ is said to satisfy the (sequential) $\Delta_{2}$-condition (on $X_{w}^{*}$ ) if the following condition holds: given a sequence $\left\{x_{n}\right\} \subset X_{w}^{*}$ and $x \in X_{w}^{*}$, if there exists a number $\lambda>0$, possibly depending on $\left\{x_{n}\right\}$ and $x$, such that $\lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0$, then $\lim _{n \rightarrow \infty} w_{\lambda / 2}\left(x_{n}, x\right)=0$.

A similar definition applies with $X_{w}^{*}$ replaced by $X_{w}$.

In the case of a metric space $(X, d)$ the modular (1.1) clearly satisfies the $\Delta_{2}$-condition on $X$.

The following important observation, which generalizes the corresponding result from the theory of classical modulars on linear spaces (cf. [22, I,5.2.IV]), provides a criterion for the metric and modular convergences to coincide.

Theorem 3.3. Given a modular $w$ on $X$, we have: the metric convergence on $X_{w}^{*}$ (with respect to $d_{w}$ if $w$ is arbitrary, and with respect to $d_{w}^{*}$ if $w$ is convex) coincides with the modular convergence iff $w$ satisfies the $\Delta_{2}$-condition on $X_{w}^{*}$.

Proof. Let $\left\{x_{n}\right\} \subset X_{w}^{*}$ and $x \in X_{w}^{*}$ be given. We know from (3.1) and Theorem 3.2 that the metric convergence (with respect to $d_{w}$ if $w$ is a modular or with respect to $d_{w}^{*}$ if $w$ is a convex modular) of $x_{n}$ to $x$ is equivalent to

$$
\begin{equation*}
\lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0 \quad \text { for all } \quad \lambda>0 \tag{3.2}
\end{equation*}
$$

$(\Rightarrow)$ Suppose that the metric convergence coincides with the modular convergence on $X_{w}^{*}$. If there exists a $\lambda_{0}>0$ such that $w_{\lambda_{0}}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$, then $x_{n}$ is modular convergent to $x$, and so, $x_{n}$ converges to $x$ in metric $\left(d_{w}\right.$ or $\left.d_{w}^{*}\right)$. It follows that (3.2) holds implying, in particular, $w_{\lambda_{0} / 2}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$, and so, $w$ satisfies the $\Delta_{2}$-condition.
$(\Leftarrow)$ By virtue of (3.2), the metric convergence on $X_{w}^{*}$ always implies the modular convergence, and so, it suffices to verify the converse assertion, namely: if $x_{n} \xrightarrow{w} x$, then (3.2) holds. In fact, if $x_{n} \xrightarrow{w} x$, then $w_{\lambda_{0}}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$ for some constant $\lambda_{0}=\lambda_{0}\left(\left\{x_{n}\right\}, x\right)>0$. The $\Delta_{2}$-condition implies $w_{\lambda_{0} / 2}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$, and so, the induction yields $w_{\lambda_{0} / 2^{j}}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$ for all $j \in \mathbb{N}$. Now, given $\lambda>0$, there exists a $j=j(\lambda) \in \mathbb{N}$ such that $\lambda>\lambda_{0} / 2^{j}$. By the monotonicity of $\lambda \mapsto w_{\lambda}\left(x_{n}, x\right)$, we have:

$$
w_{\lambda}\left(x_{n}, x\right) \leq w_{\lambda_{0} / 2^{j}}\left(x_{n}, x\right) \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty .
$$

By the arbitrariness of $\lambda>0$, condition (3.2) follows.
Definition 3.3. Given a modular $w$ on $X$, a sequence $\left\{x_{n}\right\} \subset X_{w}^{*}$ is said to be modular Cauchy (or $w$-Cauchy) if there exists a number $\lambda=\lambda\left(\left\{x_{n}\right\}\right)>0$ such that $w_{\lambda}\left(x_{n}, x_{m}\right) \rightarrow 0$ as $n, m \rightarrow \infty$, i.e.,

$$
\forall \varepsilon>0 \exists n_{0}(\varepsilon) \in \mathbb{N} \text { such that } \forall n \geq n_{0}(\varepsilon), m \geq n_{0}(\varepsilon): w_{\lambda}\left(x_{n}, x_{m}\right) \leq \varepsilon
$$

It follows from Theorem 3.2 (Step 2 in its proof) and Definition 3.3 that a sequence from $X_{w}^{*}$, which is Cauchy in metric $d_{w}$ or $d_{w}^{*}$, is modular Cauchy.

Note that a modular convergent sequence is modular Cauchy. In fact, if $x_{n} \xrightarrow{w} x$, then $w_{\lambda}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$ for some $\lambda>0$, and so, for each $\varepsilon>0$ there exists an $n_{0}(\varepsilon) \in \mathbb{N}$ such that $w_{\lambda}\left(x_{n}, x\right) \leq \varepsilon / 2$ for all $n \geq n_{0}(\varepsilon)$. It follows from (iii) that if $n, m \geq n_{0}(\varepsilon)$, then $w_{2 \lambda}\left(x_{n}, x_{m}\right) \leq$ $w_{\lambda}\left(x_{n}, x\right)+w_{\lambda}\left(x_{m}, x\right) \leq \varepsilon$, which implies that $\left\{x_{n}\right\}$ is modular Cauchy.

The following definition will play an important role below.
Definition 3.4. Given a modular $w$ on $X$, the modular space $X_{w}^{*}$ is said to be modular complete (or $w$-complete) if each modular Cauchy sequence from $X_{w}^{*}$ is modular convergent in the following (more precise) sense: if $\left\{x_{n}\right\} \subset X_{w}^{*}$ and there exists a $\lambda=\lambda\left(\left\{x_{n}\right\}\right)>0$ such that $\lim _{n, m \rightarrow \infty} w_{\lambda}\left(x_{n}, x_{m}\right)=0$, then there exists an $x \in X_{w}^{*}$ such that $\lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0$.

The notions of modular convergence, modular limit and modular completeness, introduced above, are illustrated by examples in the next section. It is clear from (1.1) that for a metric space $(X, d)$ these notions coincide with respective notions in the metric space setting.

## 4. Examples of metric and modular convergences

We begin with recalling certain properties of $\varphi$-functions and convex functions on the set of all nonnegative reals $\mathbb{R}^{+}=[0, \infty)$.

A function $\varphi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is said to be a $\varphi$-function if it is continuous, nondecreasing, unbounded (and so, $\varphi(\infty) \equiv \lim _{u \rightarrow \infty} \varphi(u)=\infty$ ) and assumes the value zero only at zero: $\varphi(u)=0$ iff $u=0$.

If $\varphi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is a convex function such that $\varphi(u)=0$ iff $u=0$, then it is (automatically) continuous, strictly increasing and unbounded, and so, it is a convex $\varphi$-function. Also, $\varphi$ is superadditive: $\varphi\left(u_{1}\right)+\varphi\left(u_{2}\right) \leq \varphi\left(u_{1}+u_{2}\right)$ for all $u_{1}, u_{2} \in \mathbb{R}^{+}$(cf. [19, Section I.1]). Moreover, $\varphi$ admits the inverse function $\varphi^{-1}: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$, which is continuous, strictly increasing, $\varphi^{-1}(u)=0$ iff $u=0$, $\varphi^{-1}(\infty)=\infty$, and which is subadditive: $\varphi^{-1}\left(u_{1}+u_{2}\right) \leq \varphi^{-1}\left(u_{1}\right)+\varphi^{-1}\left(u_{2}\right)$ for all $u_{1}, u_{2} \in \mathbb{R}^{+}$. The function $\varphi$ is said to satisfy the $\Delta_{2}$-condition at infinity (cf. [19, Section I.4]) if there exist constants $K>0$ and $u_{0} \geq 0$ such that $\varphi(2 u) \leq K \varphi(u)$ for all $u \geq u_{0}$.
4.1. Let the triple $(M, d,+)$ be a metric semigroup, i.e., the pair $(M, d)$ is a metric space with metric $d$, the pair $(M,+)$ is an Abelian semigroup
with respect to the operation of addition + , and $d$ is translation invariant in the sense that $d(p+r, q+r)=d(p, q)$ for all $p, q, r \in M$. Any normed linear space $(M,|\cdot|)$ is a metric semigroup with the induced metric $d(p, q)=|p-q|$, $p, q \in M$, and the addition operation + from $M$. If $K \subset M$ is a convex cone (i.e., $p+q, \lambda p \in K$ whenever $p, q \in K$ and $\lambda \geq 0$ ), then the triple $(K, d,+)$ is also a metric semigroup. A nontrivial example of a metric semigroup is as follows (cf. [12, 26]). Let $(Y,|\cdot|)$ be a real normed space and $M$ be the family of all nonempty closed bounded convex subsets of $Y$ equipped with the Hausdorff metric $d$ given by $d(P, Q)=\max \{\mathrm{e}(P, Q), \mathrm{e}(Q, P)\}$, where $P, Q \in M$ and $\mathrm{e}(P, Q)=\sup _{p \in P} \inf _{q \in Q}|p-q|$. Given $P, Q \in M$, we define $P \oplus Q$ as the closure in $Y$ of the Minkowski sum $P+Q=\{p+q: p \in P, q \in Q\}$. Then the triple $(M, d, \oplus)$ is a metric semigroup (actually, $M$ is an abstract convex cone). For more information on metric semigroups and their special cases, abstract convex cones, including examples we refer to [5, 6, , 9, 10] and references therein.

Given a closed interval $[a, b] \subset \mathbb{R}$ with $a<b$, we denote by $\mathbb{X}=M^{[a, b]}$ the set of all mappings $x:[a, b] \rightarrow M$. If $\varphi$ is a convex $\varphi$-function on $\mathbb{R}^{+}$, we define a function $w:(0, \infty) \times \mathbb{X} \times \mathbb{X} \rightarrow[0, \infty]$ for all $\lambda>0$ and $x, y \in \mathbb{X}$ by (note that $w$ depends on $\varphi$ )

$$
\begin{equation*}
w_{\lambda}(x, y)=\sup _{\pi} \sum_{i=1}^{m} \varphi\left(\frac{d\left(x\left(t_{i}\right)+y\left(t_{i-1}\right), x\left(t_{i-1}\right)+y\left(t_{i}\right)\right)}{\lambda \cdot\left(t_{i}-t_{i-1}\right)}\right) \cdot\left(t_{i}-t_{i-1}\right) \tag{4.1}
\end{equation*}
$$

where the supremum is taken over all partitions $\pi=\left\{t_{i}\right\}_{i=1}^{m}$ of the interval $[a, b]$, i.e., $m \in \mathbb{N}$ and $a=t_{0}<t_{1}<t_{2}<\ldots<t_{m-1}<t_{m}=b$. It was shown in [5, Sections 3, 4] that $w$ is a convex pseudomodular on $\mathbb{X}$. Thus, given $x_{0} \in M$, the modular space $\mathbb{X}_{w}^{*}=\mathbb{X}_{w}^{*}\left(x_{0}\right)$ (here $x_{0}$ denotes also the constant mapping $x_{0}(t)=x_{0}$ for all $t \in[a, b]$ ), which was denoted in [5, (3.20) and Section 4.1] by $\mathrm{GV}_{\varphi}([a, b] ; M)$ and called the space of mappings of bounded generalized $\varphi$-variation, is well defined and, by the translation invariance of $d$ on $M$, we have: $x \in \mathbb{X}_{w}^{*}=\operatorname{GV}_{\varphi}([a, b] ; M)$ iff $x:[a, b] \rightarrow M$ and there exists a constant $\lambda=\lambda(x)>0$ such that

$$
\begin{equation*}
w_{\lambda}\left(x, x_{0}\right)=\sup _{\pi} \sum_{i=1}^{m} \varphi\left(\frac{d\left(x\left(t_{i}\right), x\left(t_{i-1}\right)\right)}{\lambda\left(t_{i}-t_{i-1}\right)}\right)\left(t_{i}-t_{i-1}\right)<\infty . \tag{4.2}
\end{equation*}
$$

Note that $w_{\lambda}\left(x, x_{0}\right)$ from (4.2) is independent of $x_{0} \in M$; this value is called the generalized $\varphi_{\lambda}$-variation of $x$, where $\varphi_{\lambda}(u)=\varphi(u / \lambda), u \in \mathbb{R}^{+}$. Since
$w$ satisfies on $\mathbb{X}$ conditions (i'), (ii) and (iv) (and not (i) in general) from definition 2.1, the quantity $d_{w}^{*}$ from (2.4) is only a pseudometric on $\mathbb{X}_{w}^{*}$ and, in particular, only $d_{w}^{*}(x, x)=0$ holds for $x \in \mathbb{X}_{w}^{*}$ (note that $d_{w}^{*}(x, y)$ was denoted by $\Delta_{\varphi}(x, y)$ in [5, equality (4.5)]).
4.2. In order to "turn" (4.1) into a modular, we fix an $x_{0} \in M$ and set $X=\left\{x:[a, b] \rightarrow M \mid x(a)=x_{0}\right\} \subset \mathbb{X}$. We assert that $w$ from (4.1) is a strict convex modular on $X$. In fact, given $x, y \in X$ and $t, s \in[a, b]$ with $t \neq s$, it follows from (4.1) that

$$
\varphi\left(\frac{d(x(t)+y(s), x(s)+y(t))}{\lambda|t-s|)}\right)|t-s| \leq w_{\lambda}(x, y)
$$

and so, by the translation invariance of $d$ and the triangle inequality,

$$
\begin{align*}
|d(x(t), y(t))-d(x(s), y(s))| & \leq d(x(t)+y(s), x(s)+y(t)) \leq \\
& \leq \lambda|t-s| \varphi^{-1}\left(\frac{w_{\lambda}(x, y)}{|t-s|}\right) \tag{4.3}
\end{align*}
$$

Now, if we suppose that $w_{\lambda}(x, y)=0$ for some $\lambda>0$, then for all $t \in[a, b]$, $t \neq s=a$, we get (note that $x(a)=y(a)=x_{0}$ )

$$
d(x(t), y(t))=|d(x(t), y(t))-d(x(a), y(a))| \leq 0
$$

Thus, $x(t)=y(t)$ for all $t \in[a, b]$, and so, $x=y$ as elements of $X$.
It is clear for the modular space $X_{w}^{*}=X_{w}^{*}\left(x_{0}\right)$ that

$$
\begin{equation*}
X_{w}^{*}=\mathbb{X}_{w}^{*} \cap X=\mathrm{GV}_{\varphi}([a, b] ; M) \cap X \tag{4.4}
\end{equation*}
$$

i.e., $x \in X_{w}^{*}$ iff $x:[a, b] \rightarrow M, x(a)=x_{0}$ and (4.2) holds for some $\lambda>0$. Moreover, the function $d_{w}^{*}$ from (2.4) is a metric on $X_{w}^{*}$.
4.3. In this subsection we show that if $(M, d,+)$ is a complete metric semigroup (i.e., $(M, d)$ is complete as a metric space), then the modular space $X_{w}^{*}$ from (4.4) is modular complete in the sense of definition 3.4,

Let $\left\{x_{n}\right\} \subset X_{w}^{*}$ be a $w$-Cauchy sequence, so that $w_{\lambda}\left(x_{n}, x_{m}\right) \rightarrow 0$ as $n, m \rightarrow \infty$ for some constant $\lambda=\lambda\left(\left\{x_{n}\right\}\right)>0$. Given $n, m \in \mathbb{N}$ and $t \in[a, b], t \neq a$, it follows from (4.3) with $x=x_{n}, y=x_{m}$ and $s=a$ that (again note that $x_{n}(a)=x_{0}$ for all $n \in \mathbb{N}$ )

$$
d\left(x_{n}(t), x_{m}(t)\right) \leq \lambda(t-a) \varphi^{-1}\left(\frac{w_{\lambda}\left(x_{n}, x_{m}\right)}{t-a}\right)
$$

This estimate, the modular Cauchy property of $\left\{x_{n}\right\}$, the continuity of $\varphi^{-1}$ and the completeness of $(M, d,+)$ imply the existence of an $x:[a, b] \rightarrow M$, $x(a)=x_{0}$ (and so, $x \in X$ ), such that the sequence $\left\{x_{n}\right\}$ converges pointwise on $[a, b]$ to $x$, i.e., $\lim _{n \rightarrow \infty} d\left(x_{n}(t), x(t)\right)=0$ for all $t \in[a, b]$. We assert that $\lim _{n \rightarrow \infty} w_{\lambda}\left(x_{n}, x\right)=0$. By the (sequential) lower semicontinuity of the functional $w_{\lambda}(\cdot, \cdot)$ from (4.1) (cf. [5, assertion (4.8) on p. 27]), we get

$$
\begin{equation*}
w_{\lambda}\left(x_{n}, x\right) \leq \liminf _{m \rightarrow \infty} w_{\lambda}\left(x_{n}, x_{m}\right) \quad \text { for all } \quad n \in \mathbb{N} . \tag{4.5}
\end{equation*}
$$

Now, given $\varepsilon>0$, by the modular Cauchy condition for $\left\{x_{n}\right\}$, there is an $n_{0}(\varepsilon) \in \mathbb{N}$ such that $w_{\lambda}\left(x_{n}, x_{m}\right) \leq \varepsilon$ for all $n \geq n_{0}(\varepsilon)$ and $m \geq n_{0}(\varepsilon)$, and so,

$$
\limsup _{m \rightarrow \infty} w_{\lambda}\left(x_{n}, x_{m}\right) \leq \sup _{m \geq n_{0}(\varepsilon)} w_{\lambda}\left(x_{n}, x_{m}\right) \leq \varepsilon \text { for all } n \geq n_{0}(\varepsilon)
$$

Since the limit inferior does not exceed the limit superior (for any real sequences), it follows from the last displayed line and (4.5) that $w_{\lambda}\left(x_{n}, x\right) \leq \varepsilon$ for all $n \geq n_{0}(\varepsilon)$, i.e., $w_{\lambda}\left(x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$. Finally, since, by Theorem 3.1(a), $X_{w}^{*}$ is closed with respect to the modular convergence, we infer that $x \in X_{w}^{*}$, which was to be proved.
4.4. In order to be able to calculate explicitly, for the sake of simplicity we assume furthermore that $M=\mathbb{R}$ with $d(p, q)=|p-q|, p, q \in \mathbb{R}$, and the function $\varphi$ satisfies the Orlicz condition at infinity: $\varphi(u) / u \rightarrow \infty$ as $u \rightarrow \infty$. In this case the value $w_{1}(x, 0)$ (cf. (4.2) with $\lambda=1$ ) is known as the $\varphi$-variation of the function $x:[a, b] \rightarrow \mathbb{R}$ (in the sense of F . Riesz, Yu. T. Medvedev and W. Orlicz), the function $x$ with $w_{1}(x, 0)<\infty$ is said to be of bounded $\varphi$-variation on $[a, b]$, and we have:

$$
\begin{equation*}
w_{\lambda}(x, y)=w_{\lambda}(x-y, 0)=w_{1}\left(\frac{x-y}{\lambda}, 0\right), \quad \lambda>0, \quad x, y \in \mathbb{X}=\mathbb{R}^{[a, b]} \tag{4.6}
\end{equation*}
$$

Denote by AC $[a, b]$ the space of all absolutely continuous real valued functions on $[a, b]$ and by $\mathrm{L}^{1}[a, b]$ the space of all (equivalence classes of) Lebesgue summable functions on $[a, b]$.

The following criterion is known for functions $x:[a, b] \rightarrow \mathbb{R}$ to be in the space $\mathrm{GV}_{\varphi}[a, b]=\mathbb{X}_{w}^{*}$ (for more details see [2], [5, Sections 3, 4], [11], 20, Section 2.4], [21]): $x \in \operatorname{GV}_{\varphi}[a, b]$ iff $w_{\lambda}(x, 0)=w_{1}(x / \lambda, 0)<\infty$ for some $\lambda=\lambda(x)>0$ (i.e., $x / \lambda$ is of bounded $\varphi$-variation on $[a, b])$ iff $x \in \mathrm{AC}[a, b]$
and its derivative $x^{\prime} \in \mathrm{L}^{1}[a, b]$ (defined almost everywhere on $[a, b]$ ) satisfies the condition:

$$
\begin{equation*}
w_{\lambda}\left(x, x_{0}\right)=w_{\lambda}(x, 0)=\int_{a}^{b} \varphi\left(\frac{\left|x^{\prime}(t)\right|}{\lambda}\right) d t<\infty, \quad x_{0} \in \mathbb{R} \tag{4.7}
\end{equation*}
$$

Given $x_{0} \in \mathbb{R}$, we set $X=\left\{x:[a, b] \rightarrow \mathbb{R} \mid x(a)=x_{0}\right\}$, and so (cf. (4.4)),

$$
\begin{equation*}
X_{w}^{*}=X_{w}^{*}\left(x_{0}\right)=\left\{x \in \mathrm{GV}_{\varphi}[a, b]: x(a)=x_{0}\right\} \tag{4.8}
\end{equation*}
$$

Thus, the modular $w$ is strict and convex on $X$ and the modular space (4.8) is modular complete. Note that $X_{w}^{*}$ is not a linear subspace of $\mathrm{GV}_{\varphi}[a, b]$, which is a normed Banach algebra (cf. [3, Theorem 3.6]).
4.5. Here we present an example when the metric and modular convergences coincide. This example is a modification of Example 3.5(c) from [5]. We set $[a, b]=[0,1], M=\mathbb{R}$ and $\varphi(u)=e^{u}-1$ for $u \in \mathbb{R}^{+}$. Clearly, $\varphi$ satisfies the Orlicz condition, but does not satisfy the $\Delta_{2}$-condition at infinity.

Given a number $\alpha>0$, we define a function $x_{\alpha}:[0,1] \rightarrow \mathbb{R}$ by

$$
x_{\alpha}(t)=\alpha t(1-\log t) \quad \text { if } \quad 0<t \leq 1 \quad \text { and } \quad x_{\alpha}(0)=0 .
$$

Since $x_{\alpha}^{\prime}(t)=-\alpha \log t$ for $0<t \leq 1$, by (4.7), for any number $\lambda>0$ we find

$$
w_{\lambda}\left(x_{\alpha}, 0\right)=\int_{0}^{1} \varphi\left(\frac{\left|x_{\alpha}^{\prime}(t)\right|}{\lambda}\right) d t=\int_{0}^{1} \frac{d t}{t^{\alpha / \lambda}}-1=\left\{\begin{array}{rrr}
\infty & \text { if } & 0<\lambda \leq \alpha \\
\frac{\alpha}{\lambda-\alpha} & \text { if } & \lambda>\alpha
\end{array}\right.
$$

It follows that the modular $w$ can take infinite values (although it is strict) and that $x_{\alpha} \in X_{w}^{*}=X_{w}^{*}(0)$ for all $\alpha>0$. Also, we have:

$$
d_{w}^{*}\left(x_{\alpha}, 0\right)=\inf \left\{\lambda>0: w_{\lambda}\left(x_{\alpha}, 0\right) \leq 1\right\}=2 \alpha .
$$

Thus, if we set $\alpha=\alpha(n)=1 / n$ and $x_{n}=x_{\alpha(n)}$ for $n \in \mathbb{N}$, then we find that $d_{w}^{*}\left(x_{n}, 0\right) \rightarrow 0$ as $n \rightarrow \infty$ and $w_{\lambda}\left(x_{n}, 0\right) \rightarrow 0$ as $n \rightarrow \infty$ for all $\lambda>0$, and, in accordance with Theorem 3.2, these two convergences are equivalent.
4.6. Here we expose an example when the modular convergence is weaker than the metric convergence. Let $[a, b], M$ and $\varphi$ be as in Example 4. 5.

Given $0 \leq \beta \leq 1$, we define a function $x_{\beta}:[0,1] \rightarrow \mathbb{R}$ as follows:

$$
x_{\beta}(t)=t-(t+\beta) \log (t+\beta)+\beta \log \beta \quad \text { if } \quad \beta>0 \quad \text { and } \quad 0 \leq t \leq 1
$$

and

$$
x_{0}(t)=t-t \log t \quad \text { if } \quad 0<t \leq 1 \quad \text { and } \quad x_{0}(0)=0
$$

Since $x_{\beta}^{\prime}(t)=-\log (t+\beta)$ for $\beta>0$ and $t \in[0,1]$, we have:
$\left|x_{\beta}^{\prime}(t)\right|=-\log (t+\beta)$ if $0 \leq t \leq 1-\beta$, and $\left|x_{\beta}^{\prime}(t)\right|=\log (t+\beta)$ if $1-\beta \leq t \leq 1$, and so, by virtue of (4.7), given $\lambda>0$, we find

$$
w_{\lambda}\left(x_{\beta}, 0\right)=\int_{0}^{1} \varphi\left(\left|x_{\beta}^{\prime}(t)\right| / \lambda\right) d t=I_{1}+I_{2}-1, \quad \beta>0
$$

where

$$
I_{1}=\int_{0}^{1-\beta} \frac{d t}{(t+\beta)^{1 / \lambda}}=\left\{\begin{array}{clr}
\frac{\lambda}{\lambda-1}\left(1-\beta^{(\lambda-1) / \lambda}\right) & \text { if } & 0<\lambda \neq 1 \\
-\log \beta & \text { if } & \lambda=1
\end{array}\right.
$$

and

$$
I_{2}=\int_{1-\beta}^{1}(t+\beta)^{1 / \lambda} d t=\frac{\lambda}{\lambda+1}\left((1+\beta)^{(\lambda+1) / \lambda}-1\right) \quad \text { for all } \quad \lambda>0
$$

Also, $w_{\lambda}\left(x_{0}, 0\right)=\infty$ if $0<\lambda \leq 1$, and $w_{\lambda}\left(x_{0}, 0\right)=1 /(\lambda-1)$ if $\lambda>1$ (cf. Example 4. 5 with $\alpha=1$. Thus, $x_{\beta} \in X_{w}^{*}=X_{w}^{*}(0)$ for all $0 \leq \beta \leq 1$.

Clearly, $x_{\beta}$ converges pointwise on $[0,1]$ to $x_{0}$ as $\beta \rightarrow+0$ (actually, the first inequality in the proof of [5, Lemma 4.1(a)] shows that the convergence is uniform on $[0,1]$ ).

Now we calculate the values $w_{\lambda}\left(x_{\beta}, x_{0}\right)$ for $\lambda>0$ and $d_{w}^{*}\left(x_{\beta}, x_{0}\right)$ and invesigate their convergence to zero as $\beta \rightarrow+0$. Since

$$
\left(x_{\beta}-x_{0}\right)^{\prime}(t)=-\log (t+\beta)+\log t \quad \text { for } \quad 0<t \leq 1
$$

we have:

$$
\frac{\left|\left(x_{\beta}-x_{0}\right)^{\prime}(t)\right|}{\lambda}=\frac{\log (t+\beta)-\log t}{\lambda}=\log \left(1+\frac{\beta}{t}\right)^{1 / \lambda},
$$

and so, by virtue of (4.6) and (4.7),

$$
w_{\lambda}\left(x_{\beta}, x_{0}\right)=\int_{0}^{1} \varphi\left(\frac{\left|\left(x_{\beta}-x_{0}\right)^{\prime}(t)\right|}{\lambda}\right) d t=-1+\int_{0}^{1}\left(1+\frac{\beta}{t}\right)^{1 / \lambda} d t
$$

If $0<\lambda \leq 1$, we have

$$
\left(1+\frac{\beta}{t}\right)^{1 / \lambda} \geq 1+\frac{\beta}{t} \quad \text { and } \quad \int_{0}^{1}\left(1+\frac{\beta}{t}\right) d t=\infty
$$

and so, $w_{\lambda}\left(x_{\beta}, x_{0}\right)=\infty$ for all $0<\beta \leq 1$ and $0<\lambda \leq 1$.
Now suppose that $\lambda>1$. Then

$$
w_{\lambda}\left(x_{\beta}, x_{0}\right)=-1+\int_{0}^{\beta}\left(1+\frac{\beta}{t}\right)^{1 / \lambda} d t+\int_{\beta}^{1}\left(1+\frac{\beta}{t}\right)^{1 / \lambda} d t \equiv-1+I I_{1}+I I_{2}
$$

where

$$
\begin{aligned}
I_{1} & \leq \int_{0}^{\beta}\left(\frac{2 \beta}{t}\right)^{1 / \lambda} d t=(2 \beta)^{1 / \lambda} \int_{0}^{\beta} t^{-1 / \lambda} d t=(2 \beta)^{1 / \lambda} \cdot \frac{\lambda}{\lambda-1} \cdot \beta^{1-(1 / \lambda)}= \\
& =2^{1 / \lambda} \cdot \frac{\lambda \beta}{\lambda-1} \rightarrow 0 \quad \text { as } \quad \beta \rightarrow+0
\end{aligned}
$$

and

$$
I I_{2} \leq \int_{\beta}^{1}\left(1+\frac{\beta}{t}\right) d t=(1-\beta)-\beta \log \beta \rightarrow 1 \quad \text { as } \quad \beta \rightarrow+0
$$

It follows that $w_{\lambda}\left(x_{\beta}, x_{0}\right) \rightarrow 0$ as $\beta \rightarrow+0$ for all $\lambda>1$.
On the other hand, since $w_{\lambda}\left(x_{\beta}, x_{0}\right)=\infty$ for all $0<\beta \leq 1$ and $0<\lambda \leq 1$ (as noticed above), we get $d_{w}^{*}\left(x_{\beta}, x_{0}\right)=\inf \left\{\lambda>0: w_{\lambda}\left(x_{\beta}, x_{0}\right) \leq 1\right\} \geq 1$, and so, $d_{w}^{*}\left(x_{\beta}, x_{0}\right)$ cannot converge to zero as $\beta \rightarrow+0$.

Thus, if we set $\beta=\beta(n)=1 / n$ and $x_{n}=x_{\beta(n)}$ for $n \in \mathbb{N}$, then we find $d_{w}^{*}\left(x_{n}, x_{0}\right) \nrightarrow 0$ as $n \rightarrow \infty$, whereas $w_{\lambda}\left(x_{n}, x_{0}\right) \rightarrow 0$ as $n \rightarrow \infty$ only for $\lambda>1$.

## 5. A fixed point theorem for modular contractions

Since convex modulars play the central role in this section, we concentrate mainly on them. We begin with a characterization of $d_{w}^{*}$-Lipschitz maps on the modular space $X_{w}^{*}$ in terms of their generating convex modulars $w$.

Theorem 5.1. Let $w$ be a convex modular on $X$ and $k>0$ be a constant. Given a map $T: X_{w}^{*} \rightarrow X_{w}^{*}$ and $x, y \in X_{w}^{*}$, the Lipschitz condition $d_{w}^{*}(T x, T y) \leq k d_{w}^{*}(x, y)$ is equivalent to the following: $w_{k \lambda+0}(T x, T y) \leq 1$ for all $\lambda>0$ such that $w_{\lambda}(x, y) \leq 1$.

Proof. First, note that, given $c>0$, the function, defined by $\bar{w}_{\lambda}(x, y)=$ $w_{c \lambda}(x, y), \lambda>0, x, y \in X$, is also a convex modular on $X$ and $d_{w}^{*}=\frac{1}{c} d_{w}^{*}$ :

$$
\begin{align*}
d_{\bar{w}}^{*}(x, y) & =\inf \left\{\lambda>0: w_{c \lambda}(x, y) \leq 1\right\}=\inf \left\{\mu / c>0: w_{\mu}(x, y) \leq 1\right\}= \\
& =\frac{1}{c} d_{w}^{*}(x, y) \quad \text { for all } x, y \in X_{\bar{w}}^{*}=X_{w}^{*} \tag{5.1}
\end{align*}
$$

Necessity. We may suppose that $x \neq y$. For any $c>k$, by the assumption, we find $d_{w}^{*}(T x, T y) \leq k d_{w}^{*}(x, y)<c d_{w}^{*}(x, y)$, whence $d_{w}^{*}(T x, T y) / c<$ $d_{w}^{*}(x, y)$. It follows that if $\lambda>0$ is such that $w_{\lambda}(x, y) \leq 1$, then, by (2.4), $d_{w}^{*}(x, y) \leq \lambda$ implying, in view of (5.1),

$$
\lambda>\frac{1}{c} d_{w}^{*}(T x, T y)=\inf \left\{\mu>0: w_{c \mu}(T x, T y) \leq 1\right\}
$$

and so, $w_{c \lambda}(T x, T y) \leq 1$. Passing to the limit as $c \rightarrow k+0$, we arrive at the desired inequality $w_{k \lambda+0}(T x, T y) \leq 1$.

Sufficiency. By the assumption, the set $\left\{\lambda>0: w_{\lambda}(x, y) \leq 1\right\}$ is contained in the set $\left\{\lambda>0: w_{k \lambda}^{+}(T x, T y)=w_{k \lambda+0}(T x, T y) \leq 1\right\}$, and so, taking the infima, by virtue of (2.4), (5.1) and the equality $d_{w^{+}}^{*}=d_{w}^{*}$, we get

$$
d_{w}^{*}(x, y) \geq \frac{1}{k} d_{w^{+}}^{*}(T x, T y)=\frac{1}{k} d_{w}^{*}(T x, T y)
$$

which implies that $T$ satisfies the Lipschitz condition with constant $k$.
Theorem 5.1 can be reformulated as follows. Since (cf. [9, Theorem 3.8(a)] and (2.4)), for $\lambda^{*}=d_{w}^{*}(x, y)$,

$$
\left(\lambda^{*}, \infty\right) \subset\left\{\lambda>0: w_{\lambda}(x, y)<1\right\} \subset\left\{\lambda>0: w_{\lambda}(x, y) \leq 1\right\} \subset\left[\lambda^{*}, \infty\right)
$$

we have: $d_{w}^{*}(T x, T y) \leq k d_{w}^{*}(x, y)$ iff $w_{k \lambda}(T x, T y) \leq 1$ for all $\lambda>\lambda^{*}=d_{w}^{*}(x, y)$.
For a metric space $(X, d)$ and the modular $w$ from (1.1) on it, Theorem 5.1 gives the usual Lipschitz condition: $d(T x, T y) /(k \lambda)=w_{k \lambda}(T x, T y) \leq 1$ for all $\lambda>0$ such that $d(x, y) / \lambda=w_{\lambda}(x, y) \leq 1$, i.e., $d(T x, T y) \leq k \lambda$ for all $\lambda \geq d(x, y)$, and so, $d(T x, T y) \leq k d(x, y)$.

As a corollary of Theorem 5.1, we find that

$$
\begin{equation*}
\text { if } w_{k \lambda}(T x, T y) \leq w_{\lambda}(x, y) \text { for all } \lambda>0 \text {, then } d_{w}^{*}(T x, T y) \leq k d_{w}^{*}(x, y) \tag{5.2}
\end{equation*}
$$

in fact, it suffices to note only that if $\lambda>0$ is such that $w_{\lambda}(x, y) \leq 1$, then, by (2.1), $w_{k \lambda+0}(T x, T y) \leq w_{k \lambda}(T x, T y) \leq w_{\lambda}(x, y) \leq 1$, and apply Theorem 5.1.

Now we briefly comment on $d_{w}$-Lipschitz maps on $X_{w}^{*}$, where $w$ is a general modular on $X$ and $d_{w}$ is the metric from (2.3). Note that, given $c>0$, the function $\bar{w}_{\lambda}(x, y)=\frac{1}{c} w_{c \lambda}(x, y)$ is also a modular on $X$ and $d_{\bar{w}}=\frac{1}{c} d_{w}$ on $X_{\bar{w}}^{*}=X_{w}^{*}$. Following the lines of the proof of Theorem 5.1, we get

Theorem 5.2. If $w$ is a modular on $X$ and $k>0$, given $T: X_{w}^{*} \rightarrow X_{w}^{*}$ and $x, y \in X_{w}^{*}$, we have $d_{w}(T x, T y) \leq k d_{w}(x, y)$ iff $w_{k \lambda+0}(T x, T y) \leq k \lambda$ for all $\lambda>0$ such that $w_{\lambda}(x, y) \leq \lambda$.

The following assertion is a corollary of Theorem 5.2.

$$
\text { if } w_{k \lambda}(T x, T y) \leq k w_{\lambda}(x, y) \text { for all } \lambda>0, \text { then } d_{w}(T x, T y) \leq k d_{w}(x, y)
$$

Definition 5.1. Given a (convex) modular $w$ on $X$, a map $T: X_{w}^{*} \rightarrow X_{w}^{*}$ is said to be modular contractive (or a $w$-contraction) provided there exist numbers $0<k<1$ and $\lambda_{0}>0$, possibly depending on $k$, such that

$$
\begin{equation*}
w_{k \lambda}(T x, T y) \leq w_{\lambda}(x, y) \text { for all } 0<\lambda \leq \lambda_{0} \text { and } x, y \in X_{w}^{*} \tag{5.3}
\end{equation*}
$$

A few remarks are in order. First, by virtue of (1.1), for a metric space $(X, d)$ condition (5.3) is equivalent to the usual one: $d(T x, T y) \leq k d(x, y)$. Second, condition (5.3) is a local one with respect to $\lambda$ as compared to the assumption on the left in (5.2), and the principal inequality in it may be of the form $\infty \leq \infty$. Third, if, in addition, $w$ is strict and if we set $\infty / \infty=1$, then (5.3) is a consequence of the following: there exists a number $0<h<1$ such that

$$
\begin{equation*}
\limsup _{\lambda \rightarrow+0}\left(\sup _{x \neq y} \frac{w_{h \lambda}(T x, T y)}{w_{\lambda}(x, y)}\right) \leq 1 \tag{5.4}
\end{equation*}
$$

where the supremum is taken over all $x, y \in X_{w}^{*}$ such that $x \neq y$. In order to see this, we first note that the left hand side in (5.4) is well defined in the sense that, by virtue of ( $\mathrm{i}_{\mathrm{s}}$ ) from definition 2.1, $w_{\lambda}(x, y) \neq 0$ for all $\lambda>0$ and $x \neq y$. Choose any $k$ such that $h<k<1$. It follows from (5.4) that

$$
\lim _{\mu \rightarrow+0} \sup _{\lambda \in(0, \mu]}\left(\sup _{x \neq y} \frac{w_{h \lambda}(T x, T y)}{w_{\lambda}(x, y)}\right) \leq 1<\frac{k}{h},
$$

and so, there exists a $\mu_{0}=\mu_{0}(k)>0$ such that

$$
\sup _{x \neq y} \frac{w_{h \lambda}(T x, T y)}{w_{\lambda}(x, y)}<\frac{k}{h} \quad \text { for all } \quad 0<\lambda \leq \mu_{0}
$$

whence

$$
w_{h \lambda}(T x, T y) \leq \frac{k}{h} w_{\lambda}(x, y), \quad 0<\lambda \leq \mu_{0}, \quad x, y \in X_{w}^{*}
$$

Taking into account inequalities (2.2) and $(h / k) \lambda<\lambda$, we get

$$
w_{\lambda}(x, y) \leq \frac{(h / k) \lambda}{\lambda} w_{(h / k) \lambda}(x, y)=\frac{h}{k} w_{(h / k) \lambda}(x, y)
$$

which together with the previous inequality gives:

$$
w_{h \lambda}(T x, T y) \leq w_{(h / k) \lambda}(x, y) \quad \text { for all } \quad 0<\lambda \leq \mu_{0} \quad \text { and } \quad x, y \in X_{w}^{*} .
$$

Setting $\lambda^{\prime}=(h / k) \lambda$ and $\lambda_{0}=(h / k) \mu_{0}$ and noting that $0<\lambda^{\prime} \leq \lambda_{0}$ and $h \lambda=k \lambda^{\prime}$, the last inequality implies $w_{k \lambda^{\prime}}(T x, T y) \leq w_{\lambda^{\prime}}(x, y)$ for all $0<\lambda^{\prime} \leq \lambda_{0}$ and $x, y \in X_{w}^{*}$, which is exactly (5.3).

The main result of this paper is the following fixed point theorem for modular contractions in modular metric spaces $X_{w}^{*}$.

Theorem 5.3. Let $w$ be a strict convex modular on $X$ such that the modular space $X_{w}^{*}$ is $w$-complete, and $T: X_{w}^{*} \rightarrow X_{w}^{*}$ be a w-contractive map such that for each $\lambda>0$ there exists an $x=x(\lambda) \in X_{w}^{*}$ such that $w_{\lambda}(x, T x)<\infty$.

Then $T$ has a fixed point, i.e., $T x_{*}=x_{*}$ for some $x_{*} \in X_{w}^{*}$. If, in addition, the modular $w$ assumes only finite values on $X_{w}^{*}$, then condition (5.5) is redundant, the fixed point $x_{*}$ of $T$ is unique and for each $\bar{x} \in X_{w}^{*}$ the sequence of iterates $\left\{T^{n} \bar{x}\right\}$ is modular convergent to $x_{*}$.

Proof. Since $w$ is convex, the following inequality follows by induction from condition (iv) of definition 2.1:

$$
\begin{equation*}
\left(\lambda_{1}+\lambda_{2}+\cdots+\lambda_{N}\right) w_{\lambda_{1}+\lambda_{2}+\cdots+\lambda_{N}}\left(x_{1}, x_{N+1}\right) \leq \sum_{i=1}^{N} \lambda_{i} w_{\lambda_{i}}\left(x_{i}, x_{i+1}\right) \tag{5.6}
\end{equation*}
$$

where $N \in \mathbb{N}, \lambda_{1}, \lambda_{2}, \ldots, \lambda_{N} \in(0, \infty)$ and $x_{1}, x_{2}, \ldots, x_{N+1} \in X$. In the proof below we will need a variant of this inequality. Let $n, m \in \mathbb{N}, n>m$, $\lambda_{m}, \lambda_{m+1}, \ldots, \lambda_{n-1} \in(0, \infty)$ and $x_{m}, x_{m+1}, \ldots, x_{n} \in X$. Setting $N=n-m$,
$\lambda_{j}^{\prime}=\lambda_{j+m-1}$ for $j=1,2, \ldots, N, x_{j}^{\prime}=x_{j+m-1}$ for $j=1,2, \ldots, N+1$ and applying (5.6) to the primed lambda's and $x$ 's, we get:

$$
\begin{equation*}
\left(\lambda_{m}+\lambda_{m+1}+\cdots+\lambda_{n-1}\right) w_{\lambda_{m}+\lambda_{m+1}+\cdots+\lambda_{n-1}}\left(x_{m}, x_{n}\right) \leq \sum_{i=m}^{n-1} \lambda_{i} w_{\lambda_{i}}\left(x_{i}, x_{i+1}\right) \tag{5.7}
\end{equation*}
$$

By the $w$-contractivity of $T$, there exist two numbers $0<k<1$ and $\lambda_{0}=\lambda_{0}(k)>0$ such that condition (5.3) holds. Setting $\lambda_{1}=(1-k) \lambda_{0}$, the assumption (5.5) implies the existence of an element $\bar{x}=\bar{x}\left(\lambda_{1}\right) \in X_{w}^{*}$ such that $C=w_{\lambda_{1}}(\bar{x}, T \bar{x})$ is finite. We set $x_{1}=T \bar{x}$ and $x_{n}=T x_{n-1}$ for all integer $n \geq 2$, and so, $\left\{x_{n}\right\} \subset X_{w}^{*}$ and $x_{n}=T^{n} \bar{x}$, where $T^{n}$ designates the $n$-th iterate of $T$. We are going to show that the sequence $\left\{x_{n}\right\}$ is $w$-Cauchy. Since $k^{i} \lambda_{1}<\lambda_{1}<\lambda_{0}$ for all $i \in \mathbb{N}$, inequality (5.3) yields:

$$
w_{k^{i} \lambda_{1}}\left(x_{i}, x_{i+1}\right)=w_{k\left(k^{i-1} \lambda_{1}\right)}\left(T x_{i-1}, T x_{i}\right) \leq w_{k^{i-1} \lambda_{1}}\left(x_{i-1}, x_{i}\right)
$$

and it follows by induction that

$$
\begin{equation*}
w_{k^{i} \lambda_{1}}\left(x_{i}, x_{i+1}\right) \leq w_{\lambda_{1}}\left(\bar{x}, x_{1}\right)=C \quad \text { for all } \quad i \in \mathbb{N} . \tag{5.8}
\end{equation*}
$$

Let integers $n$ and $m$ be such that $n>m$. We set

$$
\lambda=\lambda(n, m)=k^{m} \lambda_{1}+k^{m+1} \lambda_{1}+\cdots+k^{n-1} \lambda_{1}=k^{m} \frac{1-k^{n-m}}{1-k} \lambda_{1} .
$$

By virtue of (5.7) with $\lambda_{i}=k^{i} \lambda_{1}$ and (5.8), we find

$$
w_{\lambda}\left(x_{m}, x_{n}\right) \leq \sum_{i=m}^{n-1} \frac{k^{i} \lambda_{1}}{\lambda} w_{k^{i} \lambda_{1}}\left(x_{i}, x_{i+1}\right) \leq \frac{1}{\lambda}\left(\sum_{i=m}^{n-1} k^{i} \lambda_{1}\right) C=C, \quad n>m
$$

Taking into account that

$$
\lambda_{0}=\frac{\lambda_{1}}{1-k}>k^{m} \frac{1-k^{n-m}}{1-k} \lambda_{1}=\lambda(n, m)=\lambda \quad \text { for all } \quad n>m
$$

and applying (2.2), we get:

$$
w_{\lambda_{0}}\left(x_{m}, x_{n}\right) \leq \frac{\lambda}{\lambda_{0}} w_{\lambda}\left(x_{m}, x_{n}\right) \leq k^{m} \frac{1-k^{n-m}}{1-k} \cdot \frac{\lambda_{1}}{\lambda_{0}} C \leq k^{m} C \rightarrow 0 \text { as } m \rightarrow \infty
$$

Thus, the sequence $\left\{x_{n}\right\}$ is modular Cauchy, and so, by the $w$-completeness of $X_{w}^{*}$, there exists an $x_{*} \in X_{w}^{*}$ such that

$$
w_{\lambda_{0}}\left(x_{n}, x_{*}\right) \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty
$$

Since $w$ is strict, by Theorem 3.1(b), the modular limit $x_{*}$ of the sequence $\left\{x_{n}\right\}$ is determined uniquely.

Let us show that $x_{*}$ is a fixed point of $T$, i.e., $T x_{*}=x_{*}$. In fact, by property (iii) of definition 2.1 and (5.3), we have (note that $T x_{n}=x_{n+1}$ ):

$$
\begin{aligned}
w_{(k+1) \lambda_{0}}\left(T x_{*}, x_{*}\right) & \leq w_{k \lambda_{0}}\left(T x_{*}, T x_{n}\right)+w_{\lambda_{0}}\left(x_{*}, x_{n+1}\right) \leq \\
& \leq w_{\lambda_{0}}\left(x_{*}, x_{n}\right)+w_{\lambda_{0}}\left(x_{*}, x_{n+1}\right) \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty
\end{aligned}
$$

and so, $w_{(k+1) \lambda_{0}}\left(T x_{*}, x_{*}\right)=0$. By the strictness of $w, T x_{*}=x_{*}$.
Finally, assuming $w$ to be finite valued on $X_{w}^{*}$, we show that the fixed point of $T$ is unique. Suppose $x_{*}, y_{*} \in X_{w}^{*}$ are such that $T x_{*}=x_{*}$ and $T y_{*}=y_{*}$. Then the convexity of $w$ and inequalities $k \lambda_{0}<\lambda_{0}$ and (5.3) imply

$$
w_{\lambda_{0}}\left(x_{*}, y_{*}\right) \leq \frac{k \lambda_{0}}{\lambda_{0}} w_{k \lambda_{0}}\left(x_{*}, y_{*}\right)=k w_{k \lambda_{0}}\left(T x_{*}, T y_{*}\right) \leq k w_{\lambda_{0}}\left(x_{*}, y_{*}\right)
$$

and since $w_{\lambda_{0}}\left(x_{*}, y_{*}\right)$ is finite, $(1-k) w_{\lambda_{0}}\left(x_{*}, y_{*}\right) \leq 0$. Thus, $w_{\lambda_{0}}\left(x_{*}, y_{*}\right)=0$, and by the strictness of $w$, we get $x_{*}=y_{*}$. The last assertion is clear.

It is to be noted that assumption (5.5) in Theorem 5.3 is (probably) too strong, and what we actually need for the iterative procedure to work in the proof of Theorem 5.3 is only the existence of an $\bar{x} \in X_{w}^{*}$ such that $w_{(1-k) \lambda_{0}}(\bar{x}, T \bar{x})<\infty$, where $\lambda_{0}$ is the constant from (5.3).

A standard corollary of Theorem 5.3 is as follows: if $w$ is finite valued on $X_{w}^{*}$ and an $n$-th iterate $T^{n}$ of $T: X_{w}^{*} \rightarrow X_{w}^{*}$ satisfies the assumptions of Theorem 5.3, then $T$ has a unique fixed point. In fact, by Theorem 5.3 applied to $T^{n}, T^{n} x_{*}=x_{*}$ for some $x_{*} \in X_{w}^{*}$. Since $T^{n}\left(T x_{*}\right)=T\left(T^{n} x_{*}\right)=T x_{*}$, the point $T x_{*}$ is also a fixed point of $T^{n}$, and so, the uniqueness of a fixed point of $T^{n}$ implies $T x_{*}=x_{*}$. We infer that $x_{*}$ is a unique fixed point of $T$ : if $y_{*} \in X_{w}^{*}$ and $T y_{*}=y_{*}$, then $T^{n} y_{*}=T^{n-1}\left(T y_{*}\right)=T^{n-1} y_{*}=\ldots=y_{*}$, i.e., $y_{*}$ is yet another fixed point of $T^{n}$, and again the uniqueness of a fixed point of $T^{n}$ yields $y_{*}=x_{*}$.

Another corollary of Theorem 5.3 concerns general (nonconvex) modulars $w$ on $X$ (cf. Theorem 5.4). Taking into account Theorem5.2 and its corollary, we have

Definition 5.2. Given a modular $w$ on $X$, a map $T: X_{w}^{*} \rightarrow X_{w}^{*}$ is said to be strongly modular contractive (or a strong $w$-contraction) if there exist numbers $0<k<1$ and $\lambda_{0}=\lambda_{0}(k)>0$ such that

$$
\begin{equation*}
w_{k \lambda}(T x, T y) \leq k w_{\lambda}(x, y) \text { for all } 0<\lambda \leq \lambda_{0} \text { and } x, y \in X_{w}^{*} \tag{5.9}
\end{equation*}
$$

Clearly, condition (5.9) implies condition (5.3).
Theorem 5.4. Let $w$ be a strict modular on $X$ such that $X_{w}^{*}$ is $w$-complete, and $T: X_{w}^{*} \rightarrow X_{w}^{*}$ be a strongly $w$-contractive map such that condition (5.5) holds. Then $T$ admits a fixed point. If, in addition, $w$ is finite valued on $X_{w}^{*}$, then (5.5) is redundant, the fixed point $x_{*}$ of $T$ is unique and for each $\bar{x} \in X_{w}^{*}$ the sequence of iterates $\left\{T^{n} \bar{x}\right\}$ is modular convergent to $x_{*}$.

Proof. We set $v_{\lambda}(x, y)=w_{\lambda}(x, y) / \lambda$ for all $\lambda>0$ and $x, y \in X$. It was observed in Section 2 that $v$ is a convex modular on $X$. It is also clear that $v$ is strict and the modular space $X_{v}^{*}=X_{w}^{*}$ is $v$-complete. Moreover, condition (5.9) for $w$ implies condition (5.3) for $v$, and (5.5) is satisfied with $w$ replaced by $v$. By Theorem 5.3, applied to $X$ and $v$, there exists an $x_{*} \in X_{v}^{*}=X_{w}^{*}$ such that $T x_{*}=x_{*}$. The remaining assertions are obvious.

## 6. An application of the fixed point theorem

In this section we present a rather standard application of Theorem 5.3 to the Carathéodory-type ordinary differential equations. The key interest will be in obtaining the inequality (5.3).

Given a convex $\varphi$-function $\varphi$ on $\mathbb{R}^{+}$satisfying the Orlicz condition at infinity, we denote by $\mathrm{L}^{\varphi}[a, b]$ the Orlicz space of real valued functions on $[a, b]$ (cf. [22, Chapter II]), i.e., a function $z:[a, b] \rightarrow \mathbb{R}$ (or an almost everywhere finite valued function $z$ on $[a, b]$ ) belongs to $\mathrm{L}^{\varphi}[a, b]$ provided $z$ is measurable and $\rho(z / \lambda)<\infty$ for some number $\lambda=\lambda(z)>0$, where $\rho(z)=\int_{a}^{b} \varphi(|z(t)|) d t$ is the classical Orlicz modular.

Suppose $f:[a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ is a (Carathéodory-type) function, which satisfies the following two conditions:
(C.1) for each $x \in \mathbb{R}$ the function $f(\cdot, x)=[t \mapsto f(t, x)]$ is measurable on $[a, b]$ and there exists a point $y_{0} \in \mathbb{R}$ such that $f\left(\cdot, y_{0}\right) \in \mathrm{L}^{\varphi}[a, b] ;$
(C.2) there exists a constant $L>0$ such that $|f(t, x)-f(t, y)| \leq L|x-y|$ for almost all $t \in[a, b]$ and all $x, y \in \mathbb{R}$.

Given $x_{0} \in \mathbb{R}$, we let $X_{w}^{*}$ be the modular space (4.8) generated by the modular $w$ from (4.1) under the assumptions from Section 4.4.

Consider the following integral operator

$$
\begin{equation*}
(T x)(t)=x_{0}+\int_{a}^{t} f(s, x(s)) d s, \quad x \in X_{w}^{*}, \quad t \in[a, b] \tag{6.1}
\end{equation*}
$$

Theorem 6.1. Under the assumptions (C.1) and (C.2) the operator $T$ maps $X_{w}^{*}$ into itself, and the following inequality holds in $[0, \infty]$ :

$$
\begin{equation*}
w_{L(b-a) \lambda}(T x, T y) \leq w_{\lambda}(x, y) \quad \text { for all } \lambda>0 \text { and } x, y \in X_{w}^{*} \tag{6.2}
\end{equation*}
$$

Proof. We will apply the Jensen integral inequality with the convex $\varphi$-function $\varphi$ (e.g., [24, X.5.6]) several times:

$$
\begin{equation*}
\varphi\left(\frac{1}{b-a} \int_{a}^{b}|x(t)| d t\right) \leq \frac{1}{b-a} \int_{a}^{b} \varphi(|x(t)|) d t, \quad x \in \mathrm{~L}^{1}[a, b], \tag{6.3}
\end{equation*}
$$

where the intergral in the right hand side is well defined in the sense that it takes values in $[0, \infty]$.

1. First, we show that $T$ is well defined on $X_{w}^{*}$. Let $x \in X_{w}^{*}$, i.e., $x \in \mathrm{GV}_{\varphi}[a, b]$ and $x(a)=x_{0}$. Since (cf. Section 4, 4) $x \in \mathrm{AC}[a, b]$, by virtue of (C.1) and (C.2), the composed function $t \mapsto f(t, x(t))$ is measurable on $[a, b]$. Let us prove that this function belongs to $\mathrm{L}^{1}[a, b]$. By Lebesgue's Theorem, $x(t)=x_{0}+\int_{a}^{t} x^{\prime}(s) d s$ for all $t \in[a, b]$, and so, (C.2) yields

$$
\begin{align*}
|f(t, x(t))| & \leq\left|f(t, x(t))-f\left(t, y_{0}\right)\right|+\left|f\left(t, y_{0}\right)\right| \leq \\
& \leq L\left|x(t)-y_{0}\right|+\left|f\left(t, y_{0}\right)\right| \leq \\
& \leq L \int_{a}^{b}\left|x^{\prime}(s)\right| d s+L\left|x_{0}-y_{0}\right|+\left|f\left(t, y_{0}\right)\right| \tag{6.4}
\end{align*}
$$

for almost all $t \in[a, b]$. Since $x \in X_{w}^{*}$, and so, $x \in \operatorname{GV}_{\varphi}[a, b]$, there exists a constant $\lambda_{1}=\lambda_{1}(x)>0$ such that (cf. (4.7))

$$
C_{1} \equiv w_{\lambda_{1}}\left(x, x_{0}\right)=\int_{a}^{b} \varphi\left(\frac{\left|x^{\prime}(s)\right|}{\lambda_{1}}\right) d s<\infty
$$

and since, by (C.1), $f\left(\cdot, y_{0}\right) \in \mathrm{L}^{\varphi}[a, b]$, there exists a constant $\lambda_{2}=\lambda_{2}\left(f\left(\cdot, y_{0}\right)\right)>0$ such that

$$
C_{2} \equiv \rho\left(f\left(\cdot, y_{0}\right) / \lambda_{2}\right)=\int_{a}^{b} \varphi\left(\frac{\left|f\left(t, y_{0}\right)\right|}{\lambda_{2}}\right) d t<\infty
$$

Setting $\lambda_{0}=L \lambda_{1}(b-a)+1+\lambda_{2}$ and noting that

$$
\frac{L \lambda_{1}(b-a)}{\lambda_{0}}+\frac{1}{\lambda_{0}}+\frac{\lambda_{2}}{\lambda_{0}}=1
$$

by the convexity of $\varphi$, we find (see (6.4))

$$
\begin{gathered}
\varphi\left(\frac{1}{\lambda_{0}}\left[L \int_{a}^{b}\left|x^{\prime}(s)\right| d s+L\left|x_{0}-y_{0}\right|+\left|f\left(t, y_{0}\right)\right|\right]\right) \leq \\
\leq \frac{L \lambda_{1}(b-a)}{\lambda_{0}} \varphi\left(\frac{1}{b-a} \int_{a}^{b} \frac{\left|x^{\prime}(s)\right|}{\lambda_{1}} d s\right)+\frac{1}{\lambda_{0}} \varphi\left(L\left|x_{0}-y_{0}\right|\right)+\frac{\lambda_{2}}{\lambda_{0}} \varphi\left(\frac{\left|f\left(\cdot, y_{0}\right)\right|}{\lambda_{2}}\right)
\end{gathered}
$$

and so, (6.4) and Jensen's integral inequality yield

$$
\begin{equation*}
\int_{a}^{b} \varphi\left(\frac{|f(t, x(t))|}{\lambda_{0}}\right) d t \leq \frac{L \lambda_{1}(b-a)}{\lambda_{0}} C_{1}+\frac{b-a}{\lambda_{0}} \varphi\left(L\left|x_{0}-y_{0}\right|\right)+\frac{\lambda_{2}}{\lambda_{0}} C_{2} \equiv C_{0}<\infty \tag{6.5}
\end{equation*}
$$

Now, it follows from (6.3) that

$$
\varphi\left(\frac{1}{\lambda_{0}(b-a)} \int_{a}^{b}|f(t, x(t))| d t\right) \leq \frac{1}{b-a} \int_{a}^{b} \varphi\left(\frac{|f(t, x(t))|}{\lambda_{0}}\right) d t \leq \frac{C_{0}}{b-a}
$$

implying

$$
\int_{a}^{b}|f(t, x(t))| d t \leq \lambda_{0}(b-a) \varphi^{-1}\left(\frac{C_{0}}{b-a}\right)<\infty
$$

Thus, $[t \mapsto f(t, x(t))] \in \mathrm{L}^{1}[a, b]$. As a consequence, the operator $T$ is well defined on $X_{w}^{*}$ and, by (6.1), $T x \in \mathrm{AC}[a, b]$ for all $x \in X_{w}^{*}$, which implies that the almost everywhere derivative $(T x)^{\prime}$ belongs to $\mathrm{L}^{1}[a, b]$ and satisfies

$$
\begin{equation*}
(T x)^{\prime}(t)=f(t, x(t)) \quad \text { for almost all } t \in[a, b] . \tag{6.6}
\end{equation*}
$$

2. It is clear from (6.1) that, given $x \in X_{w}^{*},(T x)(a)=x_{0}$, and so, $T x \in X=\left\{y:[a, b] \rightarrow \mathbb{R} \mid y(a)=x_{0}\right\}$. Now we show that $T x \in X_{w}^{*}$. In fact, by virtue of (4.7), (6.6) and (6.5), we have

$$
\begin{equation*}
w_{\lambda_{0}}\left(T x, x_{0}\right)=\int_{a}^{b} \varphi\left(\frac{\left|(T x)^{\prime}(t)\right|}{\lambda_{0}}\right) d t=\int_{a}^{b} \varphi\left(\frac{|f(t, x(t))|}{\lambda_{0}}\right) d t \leq C_{0} \tag{6.7}
\end{equation*}
$$

and so, $T$ maps $X_{w}^{*}$ into itself.
3. In order to obtain inequality (6.2), let $\lambda>0$ and $x, y \in X_{w}^{*}$. Taking into account (4.6), (4.7) and (6.6), we find

$$
\begin{align*}
w_{L(b-a) \lambda}(T x, T y) & =w_{L(b-a) \lambda}\left(T x-T y, x_{0}\right)=\int_{a}^{b} \varphi\left(\frac{\left|(T x-T y)^{\prime}(t)\right|}{L(b-a) \lambda}\right) d t= \\
& =\int_{a}^{b} \varphi\left(\frac{|f(t, x(t))-f(t, y(t))|}{L(b-a) \lambda}\right) d t \tag{6.8}
\end{align*}
$$

Applying (C.2) and Lebesgue's Theorem, we get, for almost all $t \in[a, b]$ $\left(\right.$ note that $\left.x(a)=y(a)=x_{0}\right)$,

$$
|f(t, x(t))-f(t, y(t))| \leq L|x(t)-y(t)| \leq L \int_{a}^{b}\left|(x-y)^{\prime}(s)\right| d s
$$

and so, by (6.3), the monotonicity of $\varphi$, (4.7) and (4.6),

$$
\begin{aligned}
\varphi\left(\frac{|f(t, x(t))-f(t, y(t))|}{L(b-a) \lambda}\right) & \leq \varphi\left(\frac{1}{b-a} \int_{a}^{b} \frac{\left|(x-y)^{\prime}(s)\right|}{\lambda} d s\right) \leq \\
& \leq \frac{1}{b-a} \int_{a}^{b} \varphi\left(\frac{\left|(x-y)^{\prime}(s)\right|}{\lambda}\right) d s= \\
& =\frac{1}{b-a} w_{\lambda}(x, y)
\end{aligned}
$$

Now, inequality (6.2) follows from (6.8).
As a corollary of Theorems 5.3 and 6.1, we have
Theorem 6.2. Under the conditions (C.1) and (C.2), given $x_{0} \in \mathbb{R}$, the initial value problem

$$
\begin{equation*}
x^{\prime}(t)=f(t, x(t)) \text { for almost all } t \in\left[a, b_{1}\right] \text { and } x(a)=x_{0} \tag{6.9}
\end{equation*}
$$

admits a solution $x \in \mathrm{GV}_{\varphi}\left[a, b_{1}\right]$ with $a<b_{1} \in \mathbb{R}$ such that $L\left(b_{1}-a\right)<1$.
Proof. We know from Section 4.4 that $w$ is a strict convex modular on the set $X=\left\{x:\left[a, b_{1}\right] \rightarrow \mathbb{R} \mid x(a)=x_{0}\right\}$ and that the modular space $X_{w}^{*}=$ $\mathrm{GV}_{\varphi}\left[a, b_{1}\right] \cap X$ is $w$-complete. By Theorem [6.1, the operator $T$ from (6.1) maps $X_{w}^{*}$ into itself and is $w$-contractive. Since the inequality $w_{k \lambda}(T x, T y) \leq$ $w_{\lambda}(x, y)$ with $0<k=L\left(b_{1}-a\right)<1$ holds for all $\lambda>0$, in the iterative
procedure in the proof of Theorem 5.3 it suffices to choose any $\bar{x} \in X_{w}^{*}$ such that $w_{\bar{\lambda}}(\bar{x}, T \bar{x})<\infty$ for some $\bar{\lambda}>0$. Since $\left(x_{0}\right)^{\prime}=0$, by virtue of (6.7) and (6.5), we find

$$
w_{\lambda_{0}}\left(T x_{0}, x_{0}\right) \leq C_{0}=\frac{b_{1}-a}{\lambda_{0}} \varphi\left(L\left|x_{0}-y_{0}\right|\right)+\frac{\lambda_{2}}{\lambda_{0}} C_{2}<\infty
$$

(the constants $\lambda_{2}$ and $C_{2}$ being evaluated on the interval $\left[a, b_{1}\right]$ ) with $\bar{\lambda}=$ $\lambda_{0}=L\left(b_{1}-a\right)+1+\lambda_{2}$, and so, we may set $\bar{x}=x_{0}$. Now, by Theorem 5.3, the integral operator $T$ admits a fixed point: the equality $T x=x$ on $\left[a, b_{1}\right]$ for some $x \in X_{w}^{*}$ is, by virtue of (6.1) and (6.6), equivalent to (6.9).

## 7. Concluding remarks

7.1. It is not our intention in this paper to study the properties of solutions to (6.9) in detail: after Theorem 6.2 on local solutions of (6.9) has been established, the questions of uniqueness, extensions, etc., of solutions can be studied following the same pattern as in, e.g., [13]. Theorems 6.1 and 6.2 are valid (with the same proofs) for mappings $x:[a, b] \rightarrow M$ and $f:[a, b] \times M \rightarrow M$ satisfying (C.1) and (C.2), where ( $M,|\cdot|$ ) is a reflexive Banach space; the details concerning the equality (4.7) in this case can be found in [2]-[5].
7.2. In the theory of the Carathéodory differential equations (6.9) (cf. [13]) the usual assumption on the right hand side is of the form $|f(t, x)| \leq g(t)$ for almost all $t \in[a, b]$ and all $x \in \mathbb{R}$, where $g \in \mathrm{~L}^{1}[a, b]$, and the resulting solution belongs to $\mathrm{AC}\left[a, b_{1}\right]$ for some $a<b_{1}<b$. However, it is known from [19, II.8] that $\mathrm{L}^{1}[a, b]=\bigcup_{\varphi \in \mathcal{N}} \mathrm{L}^{\varphi}[a, b]$, where $\mathcal{N}$ is the set of all $\varphi$-functions satisfying the Orlicz condition at infinity. Also, it follows from [2, Corollary 11] that $\mathrm{AC}[a, b]=\bigcup_{\varphi \in \mathcal{N}} \mathrm{GV}_{\varphi}[a, b]$. Thus, Theorem 6.2 reflects the regularity property of solutions of (6.9). Note that, in contrast with functions from $\mathrm{AC}[a, b]$, functions $x$ from $\mathrm{GV}_{\varphi}[a, b]$ have the "qualified" modulus of continuity ([5, Lemma 3.9(a)]): $|x(t)-x(s)| \leq C_{x} \cdot \omega_{\varphi}(|t-s|)$ for all $t, s \in[a, b]$, where $C_{x}=d_{w}^{*}(x, 0)$ and $\omega_{\varphi}: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is a subadditive function given by $\omega_{\varphi}(u)=u \varphi^{-1}(1 / u)$ for $u>0$ and $\omega_{\varphi}(+0)=\omega_{\varphi}(0)=0$.
7.3. Theorem 6.1 does not reflect all the flavour of Theorem 5.3, namely, the locality of condition (5.3) and the modular convergence of the successive approximations of the fixed points, and so, an appropriate example is yet to be found; however, one may try to adjust Example 2.15 from [16] (note that Proposition 2.14 from [16] is similar to our assertion (5.2) with $k=1$ ).

Acknowledgments. The author is grateful to Marek Balcerzak and Jacek Jachymski (Łódz Technical University, Łódz, Poland) for their keen interest and stimulating discussions on the results of this paper.

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[^0]:    ${ }^{*}$ Supported by Scientific Foundation of the National Research University Higher School of Economics, Individual Research Project No. 10-01-0071.

    Email address: czeslaw@mail.ru, vchistyakov@hse.ru (Vyacheslav V. Chistyakov)

