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On obstructions to the existence of a simple arc, connecting the multidimensional Morse-Smale diffeomorphisms¹

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Abstracts. In this paper we consider Morse-Smale diffeomorphisms defined on a multidimensional non simply connected closed manifold M^n , $n \geq 3$. For such systems, the concept of trivial (non trivial) connectedness of their periodic orbits is introduced. It is established that isotopic trivial and non trivial diffeomorphisms can not be joined by an arc with codimension one bifurcations. Examples of such pair of Morse-Smale cascades on the manifold $S^{n-1} \times S^1$ are constructed.

Keywords: Morse-Smale diffeomorphisms, bifurcation, smooth arc

1. Introduction and a formulation of results

The present paper has deal with a solution of the Palis-Pugh problem [9] on the existence of an arc with a finite or countable set of bifurcations connecting two Morse-Smale systems on a smooth closed manifold M^n . S. Newhouse and M. Peixoto [7] proved that any Morse-Smale vector fields can be connected by a simple arc. Simplicity means that the arc consists of the Morse-Smale systems with the exception in a finite set of points in which the vector field deviates by at least way (in a certain sense) from the Morse-Smale system. Below we give a definition of the simple arc for discrete Morse-Smale systems.

Let $Diff(M^n)$ be the space of diffeomorphisms on a closed manifold M^n with C^1 -topology and $MS(M^n)$ be the subset of Morse-Smale diffeomorphisms. *Smooth arc* in $Diff(M^n)$ is a smooth map

$$\xi : M^n \times [0, 1] \rightarrow M^n,$$

that is a smoothly depending on $(x, t) \in M^n \times [0, 1]$ family of diffeomorphisms

$$\{\xi_t \in Diff(M^n), t \in [0, 1]\}.$$

The arc ξ is called *simple* if $\xi_t \in MS(M^n)$ for every $t \in ([0, 1] \setminus B)$, where B is a finite set and for $t \in B$ diffeomorphisms undergo bifurcations of the following types: saddle-node, doubling period, heteroclinic tangency (see section 3 for details).

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As follows from the papers by Sh. Matsumoto [6] and P. Blanchar [1], any oriented closed surface admits isotopic Morse-Smale diffeomorphisms, who can not be connected by a simple arc. In the paper by V. Grines and O. Pochinka [3] necessary and sufficient conditions were found for the fact that the Morse-Smale diffeomorphism without heteroclinic intersections on the 3-sphere is connected by a simple arc with the “source-sink” diffeomorphism. They also constructed examples of Morse-Smale diffeomorphisms on the 3-sphere that are not joined by a simple arc due to the wild embeddings of all saddle separatrices for one of them.

In the present paper we consider diffeomorphism $f \in MS(M^n)$ which defined on a multidimensional non simply connected manifold M^n for $n \geq 3$. Through \mathcal{O}_x we denote the orbit of the point $x \in M^n$ under the diffeomorphism f .

Periodic orbits $\mathcal{O}_p, \mathcal{O}_q$ of the diffeomorphism $f \in M^n$ are called by *trivially related* if there is a curve $c \subset M^n$ such that $\partial c = \{q\} - \{p\}$ and for some integer N such that $f^N(p) = p$ and $f^N(q) = q$, closed curve $f^N(c) - c$ is homotopic to zero. Otherwise orbits $\mathcal{O}_p, \mathcal{O}_q$ are called *non trivially related*. If all periodic orbits of the diffeomorphism f are trivially related then f is called *trivial*, otherwise — *non trivial*.

In section 2 isotopic diffeomorphisms $f_0, f_1 \in MS(\mathbb{S}^{n-1} \times \mathbb{S}^1)$, $n \geq 3$ will constructed, one of which is trivial, the other is non trivial. The main result of this paper is the following theorem.

Theorem 1. *There is no simple arc connecting a trivial diffeomorphism with a non trivial diffeomorphism from the class $MS(M^n)$.*

2. The construction of a trivial-non trivial pair of isotopic diffeomorphisms

Let

$$\mathbb{S}^n = \{(x_1, x_2, \dots, x_{n+1}) \in \mathbb{R}^{n+1} : x_1^2 + x_2^2 + \dots + x_{n+1}^2 = 1\}.$$

For the sphere \mathbb{S}^1 also consider its complex form

$$\mathbb{S}^1 = \{e^{i2\pi\beta}, \beta \in [0; 1]\}.$$

Define a diffeomorphism $\phi : [0; 1] \rightarrow [0; 1]$ by the formula:

$$\phi(\beta) = \beta + \beta(\beta - 1) \left(\beta - \frac{1}{2} \right).$$

Dynamics of a diffeomorphism of the circle sending a point $e^{i2\pi\beta}$ to the point $e^{i2\pi\phi(\beta)}$ is shown in Figure 1. Notice that the diffeomorphism ϕ is isotopic to the identity since there is an isotopy $\phi_t : [0; 1] \rightarrow [0; 1]$ given by the formula:

$$\phi_t(\beta) = \beta + t\beta(\beta - 1) \left(\beta - \frac{1}{2} \right),$$

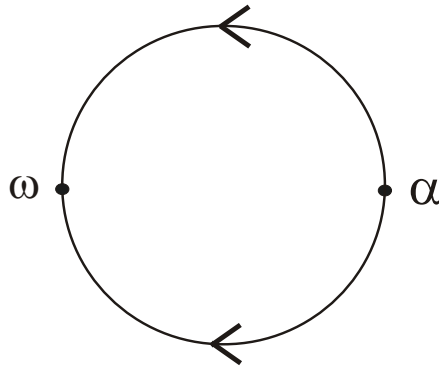


Рис. 1. Source-sink on the circle

for which $\phi_0 = id$ and $\phi_1 = g$.

For $n > 2$ let us define a diffeomorphism $\psi : \mathbb{S}^{n-1} \rightarrow \mathbb{S}^{n-1}$ by the formula:

$$\psi(x_1, x_2, \dots, x_n) = \left(\frac{4x_1}{5 - 3x_n}, \frac{4x_2}{5 - 3x_n}, \dots, \frac{5x_n - 3}{5 - 3x_n} \right).$$

Figure 2 depicts the dynamics of such a diffeomorphism for $n = 3$. The diffeomorphism

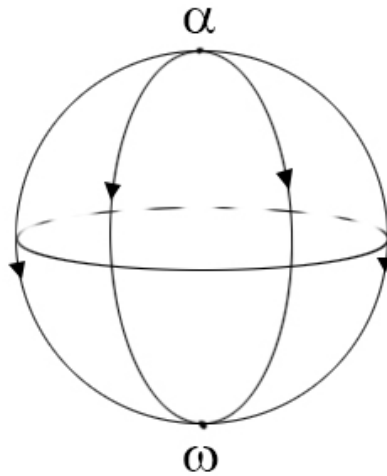


Рис. 2. Source-sink on the sphere

ψ is also isotopic to the identity since there exists an isotopy $\psi_t : \mathbb{S}^{n-1} \rightarrow \mathbb{S}^{n-1}$ given by the formula:

$$\psi_t(x_1, x_2, \dots, x_n) = \left(\frac{x_1(1 + 3t)}{t(4 - 3x_n) + 1}, \frac{x_2(1 + 3t)}{t(4 - 3x_n) + 1}, \dots, \frac{t(4 - 3) + x_n}{t(4 - 3x_n) + 1} \right),$$

for which $\psi_0 = id$ and $\psi_1 = \psi$.

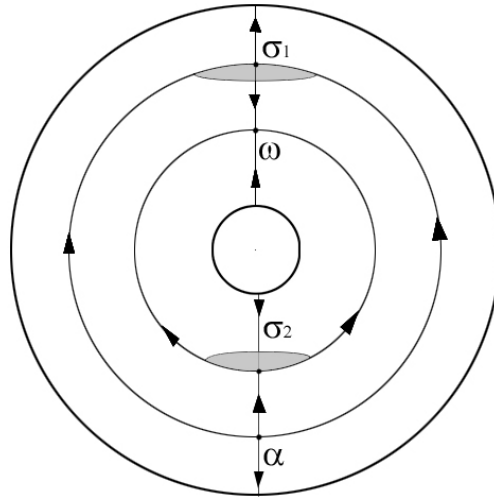


Рис. 3. Dynamic of the trivial diffeomorphism $f_0 : \mathbb{S}^2 \times \mathbb{S}^1 \rightarrow \mathbb{S}^2 \times \mathbb{S}^1$

Let us consider the Cartesian product of our spheres $\mathbb{S}^{n-1} \times \mathbb{S}^1$ and define a diffeomorphism $f_0 : \mathbb{S}^{n-1} \times \mathbb{S}^1 \rightarrow \mathbb{S}^{n-1} \times \mathbb{S}^1$ by the formula:

$$f_0(x_1, \dots, x_n, e^{i2\pi\beta}) = (\psi(x_1, \dots, x_n), e^{i2\pi\phi(\beta)}).$$

By construction, the diffeomorphism f_0 is a Morse-Smale diffeomorphism and its non-wandering set consists of one sink, one source, and two saddle points whose invariant manifolds do not intersect. Figure 3 shows a phase portrait for the case $n = 3$. Since there is an isotopy

$$f_{0,t}(x_1, \dots, x_n, e^{i2\pi\beta}) = (\psi_t(x_1, \dots, x_n), e^{i2\pi\phi_t(\beta)})$$

such that $f_{0,0} = id$ and $f_{0,1} = f_0$, hence the diffeomorphism f_0 is isotopic to the identity. In addition, it is easy to see that all its fixed points are trivially related.

On the sphere \mathbb{S}^{n-1} let us consider a subset of points (x_1, \dots, x_n) , for which $x_n \in [0, \frac{3}{5}]$ (see Figure 4 for the case $n = 3$). It is diffeomorphic to n -dimensional annulus, denote it by \mathbb{L} . In the cartesian product $\mathbb{S}^{n-1} \times \mathbb{S}^1$ we obtain a subset $\mathbb{K} = \mathbb{L} \times \mathbb{S}^1, x_n \in [0, \frac{3}{5}]$. We define a diffeomorphism $\varphi : \mathbb{S}^{n-1} \times \mathbb{S}^1 \rightarrow \mathbb{S}^{n-1} \times \mathbb{S}^1$ which is the identity outside \mathbb{K} and on \mathbb{K} is given by the formula:

$$\varphi(x_1, \dots, x_n, e^{i2\pi\beta}) = (x_1, \dots, x_n, e^{i2\pi(\beta + \frac{5}{3}x_n)}).$$

We show that the diffeomorphism φ is isotopic to the identity. To do this, we construct the isotopy φ_t as follows:

- 1) $\varphi_t = id$ on the set $\mathbb{K}^- = \{x_1, \dots, x_n, e^{i2\pi\beta} \in \mathbb{S}^{n-1} \times \mathbb{S}^1 : x_n < 0\}$;
- 2) $\varphi_t(x_1, \dots, x_n, e^{i2\pi\beta})(x_1, \dots, x_n, e^{i2\pi(\beta + \frac{5}{3}x_n t)})$ on the set \mathbb{K} ;

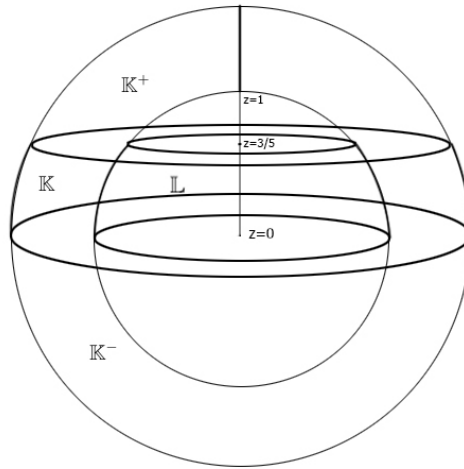


Рис. 4. The parts of $\mathbb{S}^2 \times \mathbb{S}^1$

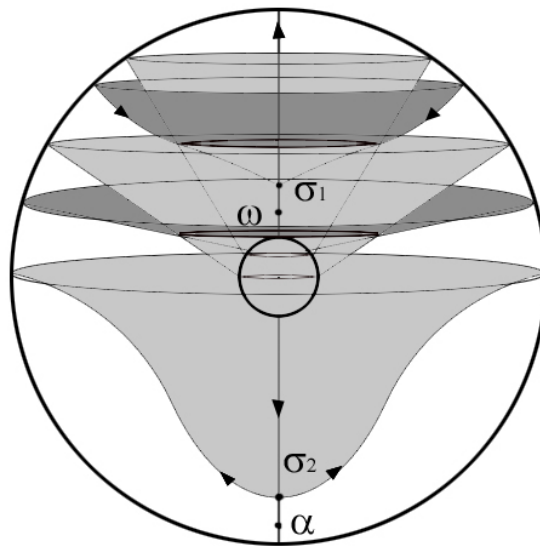


Рис. 5. Dynamic of the non trivial diffeomorphism $f_0 : \mathbb{S}^2 \times \mathbb{S}^1 \rightarrow \mathbb{S}^2 \times \mathbb{S}^1$

3) $\varphi_t(x_1, \dots, x_n, e^{i2\pi\beta}) = (x_1, \dots, x_n, e^{i2\pi(\beta+t)})$ on the set $\mathbb{K}^+ = \{(x_1, \dots, x_n, e^{i2\pi\beta}) \in \mathbb{S}^{n-1} \times \mathbb{S}^1 : x_n \in [\frac{3}{5}, 1)\}$.

From the construction of isotopy φ_t it's clear that $\varphi_0 = id, \varphi_1 = \varphi$. We define a diffeomorphism $f_1 : \mathbb{S}^{n-1} \times \mathbb{S}^1 \rightarrow \mathbb{S}^{n-1} \times \mathbb{S}^1$ formula

$$f_1 = \varphi f_0.$$

Then the diffeomorphism f_1 is isotopic to the identity by means of the isotopy $f_{1,t} = \varphi_t f_{0,t}$. By construction, the diffeomorphism f_1 is a Morse-Smale diffeomorphism, its

non-wandering set consists of one sink, one source, and two saddle points whose two-dimensional manifolds intersect along a countable set of compact heteroclinic curves. In addition, the saddle points are non trivially related. In Figure 5 we show the Morse-Smale diffeomorphism f_1 for the case $n = 3$.

3. Simple arcs

We recall that a smooth map $\xi : M^n \times [0, 1] \rightarrow M^n$ is called a simple arc if $\xi_t \in MS(M^n)$ for every $t \in ([0, 1] \setminus B)$, where B is a finite set and for $b \in B$ the diffeomorphism ξ_b undergoes one of bifurcations of the following types: saddle-node, doubling period, heteroclinic tangency. Below we give an information about these bifurcations, for exact details see, for example, [5].

Let p be a fixed point of a diffeomorphism $f : M^n \rightarrow M^n$. Differential Df_p induces a decomposition of the tangent space $T_p M^n$ into a direct sum of invariant subspaces

$$T_p M^n = E^u \oplus E^c \oplus E^s.$$

Linear maps $Df_p|_{E^u}$, $Df_p|_{E^c}$, $Df_p|_{E^s}$ have eigenvalues, respectively, outside, on the boundary, inside the unit disc. There exists a unique smooth invariant submanifold W_p^u (W_p^s) of the manifold M^n tangent to E^u (E^s) at the point p and possessing the property

$$W_p^u = \{y \in M^n : \lim_{k \rightarrow -\infty} f^k(y) = p\} \quad (W_p^s = \{y \in M^n : \lim_{k \rightarrow +\infty} f^k(y) = p\}).$$

It is called by *unstable (stable) manifold* of the point p . In particular, if $\dim E^c = 0$, the point p is *hyperbolic*. Otherwise, there exists a smooth invariant submanifold W_p^c of the manifold M^n tangent to E^c at the point p . It is called the *central manifold* of a non hyperbolic fixed point. A central manifold is not unique but the maps $f|_{W_p^c}$ and $f|_{\tilde{W}_p^c}$ are topologically conjugated for any central manifolds W_p^c and \tilde{W}_p^c .

The *central, stable and unstable manifolds* of a periodic point of period k is defined as the corresponding manifolds of this point as a fixed point of the diffeomorphism f^k .

For a typical set of arcs ξ , the diffeomorphism ξ_b , $b \in B$, under the direction of motion along the arc, undergoes one of the bifurcations described below. In the explanatory drawings, double arrows schematically show the directions of motion with exponential contraction and expansion, and single directions indicate the directions of motion along the central manifold of the non hyperbolic point.

1) All periodic orbits of the diffeomorphism ξ_b are hyperbolic with an exception in a one orbit \mathcal{O}_p of the period k for which all eigenvalues of $(Df^k)_p$ different from 1 by absolute values except one $\lambda = 1$. The stable and the unstable manifolds of different periodic orbits of the diffeomorphism ξ_b intersect transversely and $W_p^s \cap W_p^u = \{p\}$. The transition through ξ_b is accompanied by a confluence and further disappearance of hyperbolic periodic points of the same period. This bifurcation is called *saddle-node* (see Figure ??).

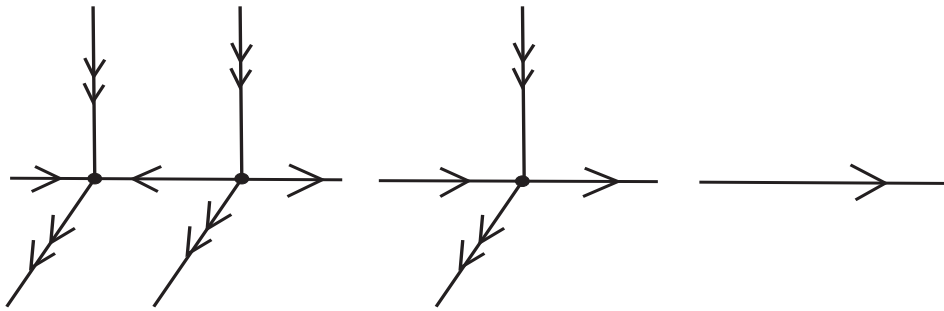


Рис. 6. Saddle-node bifurcation

2) All periodic orbits of the diffeomorphism ξ_b are hyperbolic with an exception in a one orbit \mathcal{O}_p of the period k for which all eigenvalues of $(Df^k)_p$ different from 1 by the absolute value except one $\lambda = -1$. The stable and the unstable manifolds of different periodic orbits of the diffeomorphism ξ_b intersect transversely and $W_p^s \cap W_p^u = \{p\}$. By passing through ξ_b along the central manifold an attractor becomes a repeller and a periodic hyperbolic orbit of the period $2k$ is generated. Such a bifurcation is called a *doubling period* (see Figure 3).

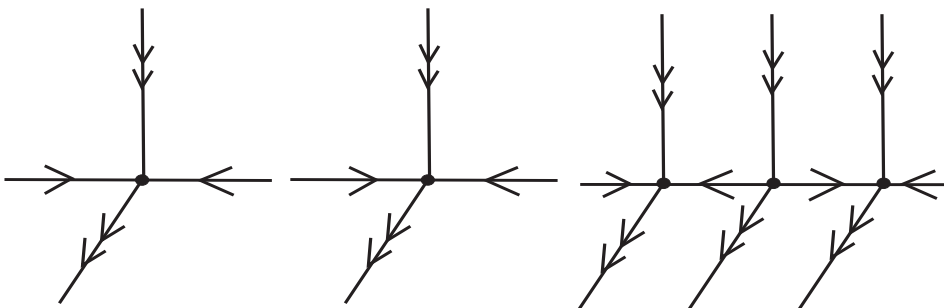


Рис. 7. Doubling period bifurcation

3) All periodic orbits of the diffeomorphism ξ_b are hyperbolic, their stable and unstable manifolds have transversal intersections everywhere except for one trajectory along which the intersection is quasi-transversal. Such a bifurcation is called a *bifurcation of a heteroclinic tangency* (see Figure 3).

4. Proof of the main result

In this section we prove Theorem 1. Namely, we consider two Morse-Smale diffeomorphisms f_0, f_1 given on a non simply connected n -manifold M^n such that f_0 is a trivial and the diffeomorphism f_1 is a non trivial. Let us prove that there is no simple arc joining the diffeomorphisms f_0 and f_1 .

Proof. Assume the contrary: f_0 and f_1 can be joined by a simple arc. Then on this arc there are two Morse-Smale diffeomorphisms g_0 and g_1 such that:

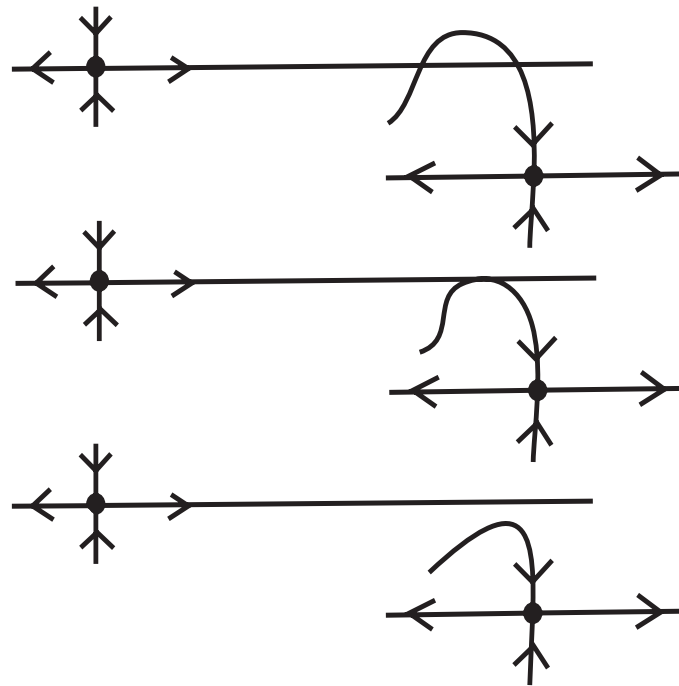


Рис. 8. Bifurcation of the heteroclinic tangency

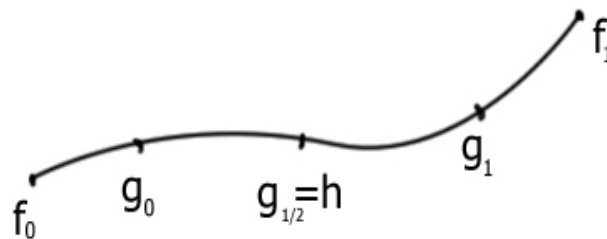


Рис. 9.

1) g_0 and g_1 can be connected with a simple arc $\{g_t\}_{t \in [0,1]}$ with only one bifurcation point, $g_{\frac{1}{2}} = h$ (see Figure 9);

2) g_0 is a trivial diffeomorphism, g_1 — non trivial.

From the description of possible for a simple arc bifurcations (see the section 3) it follows that the non-wandering set Ω_h of the diffeomorphism h has a periodic orbit saddle-node \mathcal{O}_p that is non trivially related to some (and, consequently, with any) other periodic orbit; in a comparison with the Morse-Smale diffeomorphism $g_t, 0 \leq t < \frac{1}{2}$, two periodic orbits of the different indexes appear for the Morse-Smale diffeomorphism $g_t, \frac{1}{2} < t < 1$.

Let $m, k \in \mathbb{N}$ be the dimensions of the unstable, stable manifolds W_p^u, W_p^s of the

point p . Then $m + k = n + 1$. By an analogy with the properties of Morse-Smale diffeomorphisms (see, for example, [2] Theorem 2.1), one can establish that

$$M^n = \bigcup_{x \in \Omega_h} W_x^u = \bigcup_{x \in \Omega_h} W_x^s.$$

Since there are no cycles for the diffeomorphism h , there are hyperbolic points $q, r \in \Omega_h$ such that $W_p^u \cap W_q^s \neq \emptyset, W_p^s \cap W_r^u \neq \emptyset$. From the transversality of the intersection of the stable and the unstable manifolds of non-wandering points of the diffeomorphism h it follows that $\dim W_q^s \geq n - m, \dim W_p^u \geq n - k$. Wherein $\dim W_q^s$ can not be strictly greater than $n - m$ and $\dim W_p^u$ can not be strictly greater than $n - k$, since in this case the point p would be trivially related to the point q (r) along the heteroclinic curve, which contradicts the properties of the diffeomorphism h described above. In this way, $\dim W_q^s = n - m, \dim W_p^u = n - k$ and consequently, $\dim W_q^s + \dim W_p^u = 2n - (m + k) = n - 1$.

Then, on the one hand, the points of invariant manifolds are arbitrarily close to the point p and, therefore, are close each to other, this means that $W_q^s \cap W_p^u \neq \emptyset$. On the other hand, from dimensional considerations, the intersection $W_q^s \cap W_p^u$ can not be transversal. We get a contradiction with the properties of the diffeomorphism h . Thus, there is no simple arc between the diffeomorphisms f_0 and f_1 . \square

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