

On embedding Morse–Smale diffeomorphisms on the sphere in topological flows

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One important indicator of the adequacy of a numerical solution of an autonomous system of differential equations is the topological conjugacy of the discrete model obtained to the time-one shift map of the original flow. The most significant results in this direction have been obtained for structurally stable flows. In particular, it was shown in [1] and [2] that the Runge–Kutta discretization of a Morse–Smale flow ($n \geq 2$) without periodic trajectories on the n -disk is topologically conjugate to the time-one shift (for a sufficiently small step size). In this connection the question, going back to Palis [3], of necessary and sufficient conditions for embedding a Morse–Smale diffeomorphism in a topological flow arises naturally.

Recall that a diffeomorphism f on a closed manifold M^n is called a *Morse–Smale diffeomorphism* if its non-wandering set Ω_f is finite and consists of hyperbolic periodic points, and for any two points $p, q \in \Omega_f$ the intersection of the stable manifold W_p^s of p and the unstable manifold W_q^u of q is transversal. In [3] the following necessary conditions for embedding a Morse–Smale diffeomorphism $f: M^n \rightarrow M^n$ in a topological flow were stated, and we call them the *Palis conditions*: 1) the non-wandering set Ω_f coincides with the set of fixed points; 2) the restriction of the diffeomorphism f to each invariant manifold of each fixed point $p \in \Omega_f$ preserves its orientation; 3) if for any distinct saddle points $p, q \in \Omega_f$ the intersection $W_p^s \cap W_q^u$ is non-empty, then it contains no compact connected components.

According to [3], in the case when $n = 2$ these conditions are not only necessary but also sufficient. In [4] examples of Morse–Smale diffeomorphisms on the three-dimensional sphere were constructed that satisfy the Palis conditions but do not embed in topological flows, and also necessary and sufficient conditions were obtained for embedding a three-dimensional Morse–Smale diffeomorphism in a topological flow. An additional obstruction to embedding such diffeomorphisms in topological flows is connected with the possibility of a non-trivial embedding of the separatrices of saddle points in the ambient manifold. In the present paper we show that for the class $G(S^n)$ of Morse–Smale diffeomorphisms without heteroclinic intersections defined on the sphere S^n of dimension $n \geq 4$ and satisfying the Palis conditions no such obstruction exists and the following theorem holds.

Theorem 1. *Any diffeomorphism $f \in G(S^n)$, $n \geq 4$, is embedded in a topological flow.*

The main tool of the proof is the scheme of a diffeomorphism, defined below. Let $f \in G(S^n)$. It follows from the connection between the dynamics of the diffeomorphism f and the homologies of the sphere S^n that for any saddle point of f either the stable or the unstable manifold has dimension 1. Denote by A_f and R_f the unions of the closures

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of the unstable and the stable one-dimensional invariant manifolds of the saddle points, respectively; if f has no saddle points with one-dimension unstable (stable) manifolds, then it has a unique sink (source) fixed point, which we also denote by A_f (R_f). Let $V_f = M^n \setminus (A_f \cup R_f)$. According to [5], the sets A_f , R_f , and V_f are connected, and A_f is an attractor, R_f is a repeller, and V_f consists of the wandering points of f going from R_f to A_f and contains all the saddle separatrices of codimension 1.

Denote by $\widehat{V}_f = V_f/f$ the orbit space of the f -action on V_f , by $p_f: V_f \rightarrow \widehat{V}_f$ the natural projection, and by $\eta_f: \pi_1(\widehat{V}_f) \rightarrow \mathbb{Z}$ the epimorphism induced by p_f . Let \widehat{L}_f^s and \widehat{L}_f^u denote the unions of the projections onto \widehat{V}_f of all the stable and unstable separatrices of the saddle points, respectively. The set $S_f = (\widehat{V}_f, \eta_f, \widehat{L}_f^s, \widehat{L}_f^u)$ is called the *scheme of the diffeomorphism* $f \in G(S^n)$. The schemes S_f and $S_{f'}$ of diffeomorphisms $f, f' \in G(S^n)$ are said to be *equivalent* if there exists a homeomorphism $\widehat{\varphi}: \widehat{V}_f \rightarrow \widehat{V}_{f'}$ with the following properties: 1) $\eta_f = \eta_{f'} \widehat{\varphi}_*$; 2) $\widehat{\varphi}(\widehat{L}_f^s) = \widehat{L}_{f'}^s$ and $\widehat{\varphi}(\widehat{L}_f^u) = \widehat{L}_{f'}^u$.

According to [6], the scheme is a complete topological invariant for diffeomorphisms in $G(S^n)$. The key and most non-trivial point for embedding a diffeomorphism $f \in G(S^n)$, $n \geq 4$, in a flow is the equivalence of the scheme S_f to the following standard object. Let a_0^t be a flow on $\mathbb{R}^n \setminus \{O\}$ defined by the formula $a_0^t(x_1, \dots, x_n) = (2^{-t}x_1, \dots, 2^{-t}x_n)$, let a_0 be the time-one shift along trajectories of a_0^t , let \widehat{V}_{a_0} be the orbit space of the a_0 -action on $\mathbb{R}^n \setminus \{O\}$ (which is diffeomorphic to $\mathbb{S}^{n-1} \times \mathbb{S}^1$), and let $p_{\widehat{V}_{a_0}}: \mathbb{R}^n \setminus \{O\} \rightarrow \widehat{V}_{a_0}$ be the natural projection. On the unit sphere $\mathbb{S}^{n-1} \subset \mathbb{R}^n$ we choose smooth pairwise disjoint $(n-2)$ -spheres $S_1^{n-2}, \dots, S_k^{n-2}$. Let $\tilde{c}_i = \bigcup_{t \in \mathbb{R}} a_0^t(S_i^{n-2})$ and $c_i = p_{\widehat{V}_{a_0}}(\tilde{c}_i)$. We choose an integer $m \in [0, k]$ and let $\widehat{L}_{a_0}^s = \bigcup_{i=1}^m c_i$ and $\widehat{L}_{a_0}^u = \bigcup_{i=m+1}^k c_i$. The set $S_{a_0} = \{\widehat{V}_{a_0}, \eta_{\widehat{V}_{a_0}}, \widehat{L}_{a_0}^s, \widehat{L}_{a_0}^u\}$ is called the *standard scheme*.

Lemma. *The scheme S_f of a diffeomorphism $f \in G(S^n)$, $n \geq 4$, is equivalent to the standard scheme for some k and m .*

This lemma allows one to use the method in [4] to construct a flow X^t whose time-one shift has a scheme equivalent to S_f . Since the scheme is a complete invariant, there exists a homeomorphism $h: S^n \rightarrow S^n$ such that $f = hX^1h^{-1}$. Hence f is embedded in the flow $Y^t = hX^th^{-1}$.

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